

2/18/2014

Ex  $\int_2^4 x^2 dx$  evaluate using Midpoint Rule with  $n=4$  and  $u=8$ .

$n=4$

$$\int_2^4 x^2 dx \approx f(m_1)\Delta x + f(m_2)\Delta x +$$

$$+ f(m_3)\Delta x + f(m_4)\Delta x \quad \textcircled{=}$$

$$f(x) = x^2, \quad \Delta x = \frac{b-a}{n} = \frac{4-2}{4} = \frac{1}{2}$$

$$x_0 = 2, \quad x_1 = 2.5, \quad x_2 = 3, \quad x_3 = 3.5, \quad x_4 = 4$$

$$m_1 = 2.25, \quad m_2 = 2.75, \quad m_3 = 3.25, \quad m_4 = 3.75$$

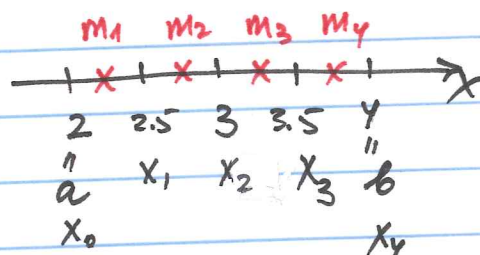
$$M(4) \textcircled{=} (f(m_1) + f(m_2) + f(m_3) + f(m_4)) \Delta x =$$

$$= (m_1^2 + m_2^2 + m_3^2 + m_4^2) \Delta x = (2.25^2 + 2.75^2 + 3.25^2 + 3.75^2) \cdot \frac{1}{2} = \boxed{18.625}$$

$$\text{Exact } \int_2^4 x^2 dx = \left. \frac{x^3}{3} \right|_2^4 = \boxed{\frac{56}{3}}$$

$$\text{abs. error} = \left| \frac{56}{3} - 18.625 \right| = \boxed{0.041666\dots} \approx 0.0417$$

$$\text{rel. error} = \left| \frac{\frac{56}{3} - 18.625}{\frac{56}{3}} \right| \approx 0.0022321\dots \approx 0.22321\%$$



$$a=2, \quad b=4$$

$$n=8$$

$$M(8) = 18.65625$$

$$\text{abs. error} = \left| \frac{56}{3} - 18.65625 \right| = \boxed{0.0104166\dots}$$

$$\sim \frac{1}{4} \text{ abs. er}_{n=4}$$

$$\Delta x \rightarrow \frac{\Delta x}{2} \Rightarrow \text{er}_{\frac{\Delta x}{2}} \sim \frac{1}{4} \text{er}_{\Delta x}$$

$$\text{rel. error} = \left| \frac{\frac{56}{3} - 18.65625}{\frac{56}{3}} \right| \approx 5.580357 \times 10^{-4}$$

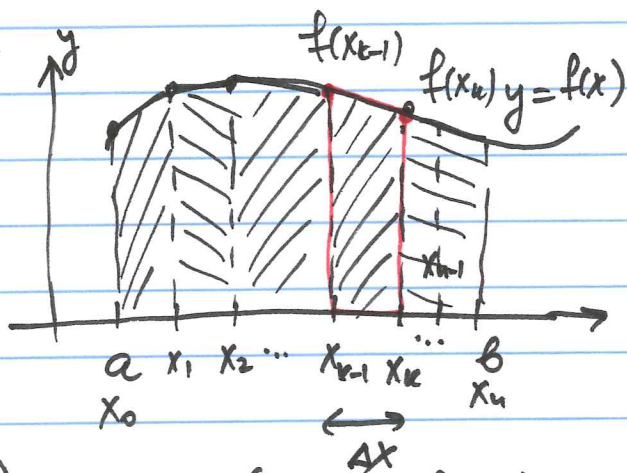
$$\approx 5.58 \cdot 10^{-2} \%$$

### Trapezoid Rule

$$A = \frac{1}{2} (f(x_{k-1}) + f(x_k)) \Delta x$$



$$\Delta x = \frac{b-a}{n}$$



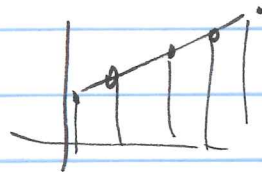
$$\int_a^b f(x) dx \approx \frac{1}{2} (f(x_0) + f(x_1)) \Delta x + \frac{1}{2} (f(x_1) + f(x_2)) \Delta x + \dots$$

$$+ \frac{1}{2} (f(x_{n-2}) + f(x_{n-1})) \Delta x + \frac{1}{2} (f(x_{n-1}) + f(x_n)) \Delta x =$$

$$\boxed{T(n) = \left( \frac{1}{2} f(x_0) + f(x_1) + f(x_2) + \dots + f(x_{n-1}) + \frac{1}{2} f(x_n) \right) \Delta x}$$

Trapezoid Rule

$$\int_a^b f(x) dx = \underbrace{T(n)}_{\text{exact}} + \underbrace{\frac{f''(\xi)}{12}}_{\text{approx.}} (b-a) (\Delta x)^2 \quad \text{error}$$



$$\text{let } |f''(\xi)| \leq k, \quad a \leq \xi \leq b$$

$$\Rightarrow |\text{error}_T| \leq \frac{k}{12} (b-a) (\Delta x)^2$$

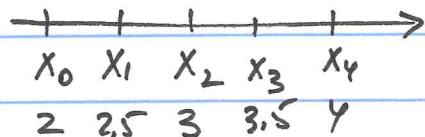
$$\text{error}_T \sim C \cdot (\Delta x)^2$$

Note: trapezoid rule is exact for linear functions

$$\Rightarrow \Delta x \rightarrow \frac{\Delta x}{2} \Rightarrow \text{error} \rightarrow \frac{1}{4} \text{ error}$$

Ex Apply Trapezoid Rule w/  $n=4$  to evaluate

$$\int_2^4 x^2 dx \approx T(4)$$



$$T(4) = \left( \frac{1}{2} f(x_0) + f(x_1) + f(x_2) + f(x_3) + \frac{1}{2} f(x_4) \right) \Delta x \quad \text{⊖}$$

$$\Delta x = \frac{4-2}{4} = \frac{1}{2}, \quad f(x) = x^2$$

$$\text{⊖} \left( \frac{1}{2} x_0^2 + x_1^2 + x_2^2 + x_3^2 + \frac{1}{2} x_4^2 \right) \Delta x =$$

$$= \left( \frac{1}{2} \cdot 2^2 + 2.5^2 + 3^2 + 3.5^2 + \frac{1}{2} 4^2 \right) \cdot \frac{1}{2} = \boxed{18.75}$$

$$\text{abs. error} = \left| \frac{56}{3} - 18.75 \right| = \boxed{0.0833} \quad \approx \text{twice larger than error w/ midpoint rule}$$

$$\text{rel. error} = \left| \text{abs. error} \right| / \left| \frac{56}{3} \right| = 0.00446 \text{ or } 0.446\%$$



Ex  $\int_0^1 x e^{-x} dx = 1 - 2e^{-1} = 0.2642117657115$

n	M(n)	T(n)	Er M(n)	Er T(n)
4	0.26683456	0.259045	0.00259 $\sim x^2$	0.00520 $\sim x^2$
8	0.2648914	0.26293980	0.000650 $\sim x^{1/2}$	0.00130 $\sim x^{1/2}$
16	0.264403836	0.2639156480	0.000163 $\sim x^{1/2}$	0.000325
32	0.264281805	0.2641597404	0.0000407	0.0000814
64	0.2642512900	0.2642207703	0.0000102	0.0000203
128	0.2642436608	0.264236031	0.00000254	0.00000509

Simpson's Rule

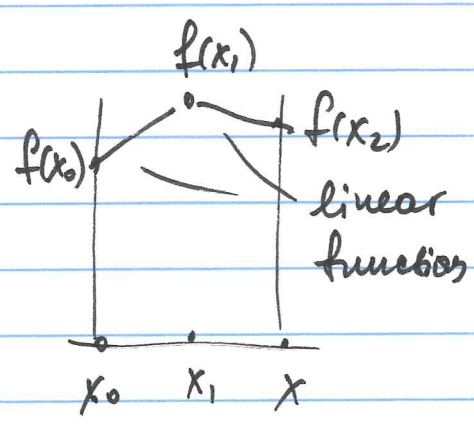
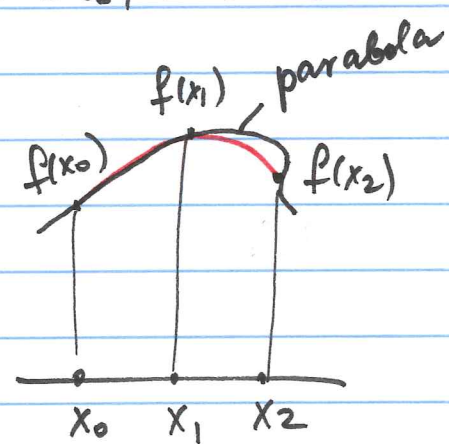
$$\int_a^b f(x) dx \approx S(n) =$$

$$= (f(x_0) + 4f(x_1) + 2f(x_2) +$$

$$+ 4f(x_3) + \dots + 2f(x_{n-2}) +$$

$$+ 4f(x_{n-1}) + f(x_n)) \Delta x / 3$$

n: even



Note

$$S(2n) = \frac{4T(2n) - T(n)}{3} = T(2n) + \frac{T(2n) - T(n)}{3}$$

gives more accurate approximation than  $T(n)$



$$\int_a^b f(x) dx = \underbrace{S(n)}_{\text{approx.}} + \underbrace{\frac{f^{(4)}(\xi)(b-a)}{180}}_{\text{error}} (\Delta x)^4$$

*a exact*

$$\text{error} \sim C \cdot (\Delta x)^4$$

$$\Delta x \rightarrow \frac{\Delta x}{2} \Rightarrow \text{error} \rightarrow \frac{1}{16} \text{ error}$$
$$\left(\frac{1}{2}\right)^4$$

2/20/2014

## 8.7 Improper Integrals

We know how to treat definite integrals of the form  $\int_a^b f(x) dx$



$[a, b]$ : finite interval

$f(x)$  assumes finite values on  $[a, b]$

Such integrals are called proper integrals.

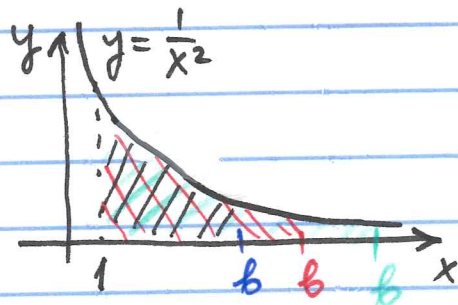
Improper integral is when either

- interval of integration is infinite or/and

- integrand  $f(x)$  is unbounded on interval of integration.

Ex

$$\int_1^b \frac{1}{x^2} dx, \quad b > 1$$



$$= -\frac{1}{x} \Big|_1^b = -\left(\frac{1}{b} - 1\right) = 1 - \frac{1}{b}$$

as  $b \nearrow$ , area under curve  $y = \frac{1}{x^2}$  also  $\nearrow$



Q What happens when  $b \rightarrow \infty$ ?

$$\lim_{b \rightarrow \infty} \left(1 - \frac{1}{b}\right) = 1$$

Note Curve  $y = \frac{1}{x^2}$  has infinite length but  
a region bounded by this curve is  
 finite and has area = 1

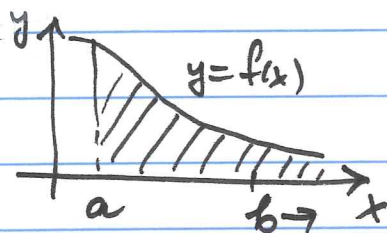
We write this

$$\int_1^{\infty} \frac{1}{x^2} dx = 1 : \text{improper integral because of } \infty \text{ upper limit}$$

1. If  $f(x)$  is continuous (CTS) on  $[a, \infty)$ ,  
 then

$$\int_a^{\infty} f(x) dx \stackrel{\text{def}}{=} \lim_{b \rightarrow \infty} \int_a^b f(x) dx$$

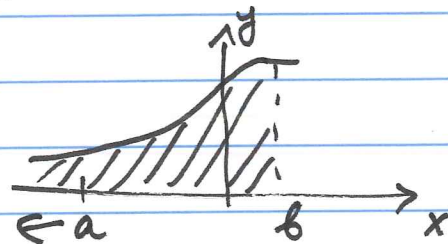
if limit exists.



2. If  $f(x)$  is CTS on  $(-\infty, b]$ ,

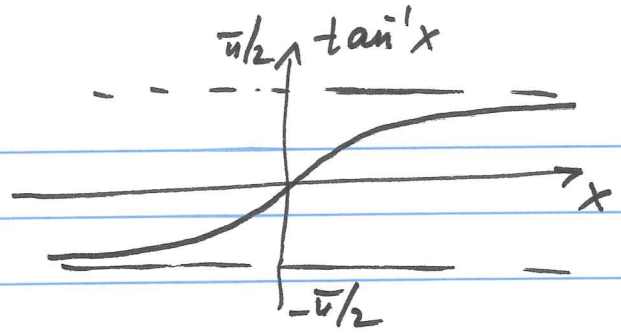
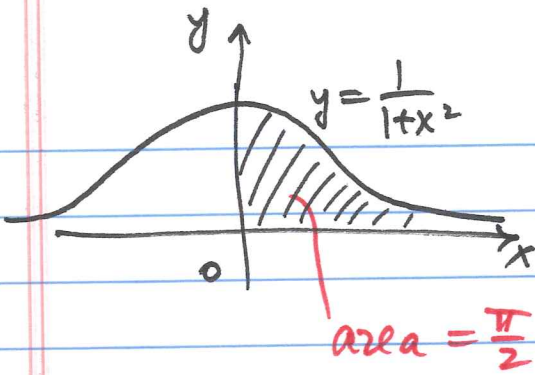
$$\text{then } \int_{-\infty}^b f(x) dx \stackrel{\text{def}}{=} \lim_{a \rightarrow -\infty} \int_a^b f(x) dx$$

if limit exists.









Ex The family  $f(x) = \frac{1}{x^p}$ ,  $p$  is a real #

Q For which  $p$ ,  $\int_1^{\infty} \frac{dx}{x^p}$  converges?

Assume  $p > 0$ .

$$\int_1^{\infty} \frac{dx}{x^p} \stackrel{\text{def}}{=} \lim_{b \rightarrow \infty} \int_1^b \frac{dx}{x^p} = \lim_{b \rightarrow \infty} \frac{1}{-p+1} x^{-p+1} \Big|_1^b =$$

$$= \frac{1}{1-p} \lim_{b \rightarrow \infty} (b^{1-p} - 1)$$

Case 1:  $p > 1$   $\Rightarrow 1-p < 0$  or  $p-1 > 0$

$$b^{1-p} = \frac{1}{b^{p-1}} \Rightarrow \lim_{b \rightarrow \infty} b^{1-p} = 0$$

$b \rightarrow \infty$

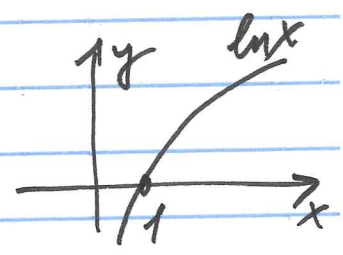
$$\int_1^{\infty} \frac{dx}{x^p} = \frac{1}{1-p} \lim_{b \rightarrow \infty} (b^{1-p} - 1) = \frac{1}{p-1} : \text{converges}$$

Case 2:  $0 < p < 1 \Rightarrow 1-p > 0 \Rightarrow b^{1-p} \xrightarrow{b \rightarrow \infty} \infty$

$\therefore \int_1^{\infty} \frac{dx}{x^p} = \frac{1}{1-p} \lim_{b \rightarrow \infty} (b^{1-p} - 1) = \infty$ : diverges

Case 3:  $p = 1$

$\int_1^{\infty} \frac{dx}{x^p} = \int_1^{\infty} \frac{dx}{x} = \lim_{b \rightarrow \infty} \int_1^b \frac{dx}{x} = \lim_{b \rightarrow \infty} \ln x \Big|_1^b =$   
 $= \lim_{b \rightarrow \infty} (\ln b - \ln 1) = \infty$ : diverges

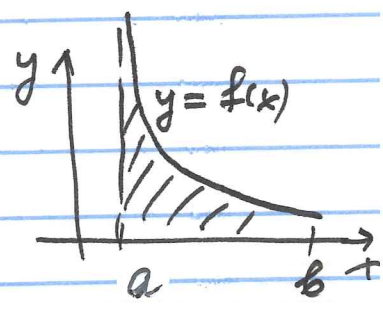


Summary:

$\int_1^{\infty} \frac{dx}{x^p} = \begin{cases} \frac{1}{p-1}, & p > 1 : \text{converges} \\ \text{diverges} & \text{otherwise} \\ & 0 < p \leq 1 \end{cases}$

Unbounded integrands

- Suppose  $f$  is cts on  $(a, b]$  and  $\lim_{x \rightarrow a^+} f(x) = \pm \infty$ . Then



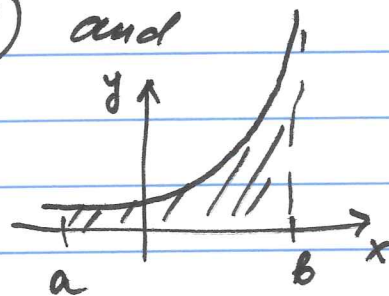


$$\int_a^b f(x) dx \stackrel{\text{def}}{=} \lim_{c \rightarrow a^+} \int_c^b f(x) dx$$

if limit exists.

2. Suppose  $f$  is CRS on  $[a, b)$  and

$$\lim_{x \rightarrow b^-} f(x) = \pm \infty$$



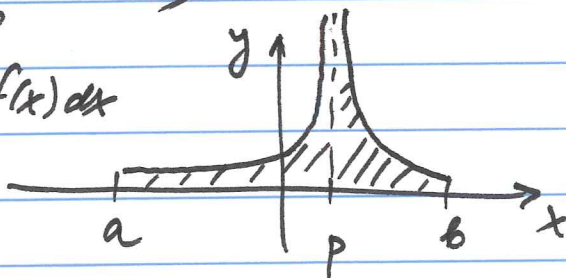
Then

$$\int_a^b f(x) dx = \lim_{c \rightarrow b^-} \int_a^c f(x) dx$$

if limit exists.

3. If  $f(x)$  is CRS on  $[a, b]$  except at pt  $p$  where  $f$  is unbounded, then

$$\int_a^b f(x) dx = \int_a^p f(x) dx + \int_p^b f(x) dx$$



if limits exist.

If the limit is finite, we say that improper integral converges, otherwise it diverges.

Ex  $f(x) = \frac{1}{\sqrt{9-x^2}}$ ,  $x \in [-3, 3]$ .

$$-3 \leq x \leq 3$$

$$\int_{-3}^3 \frac{dx}{\sqrt{9-x^2}} = 2 \int_0^3 \frac{dx}{\sqrt{9-x^2}} \stackrel{\text{def}}{=} 2 \lim_{c \rightarrow 3^-} \int_0^c \frac{dx}{\sqrt{9-x^2}} \quad \textcircled{\ominus}$$

(even)

$$f(-x) = f(x) \quad \begin{array}{c} | \quad | \\ \hline 0 \quad \rightarrow \quad 3 \end{array}$$

Recall  $\int \frac{dx}{\sqrt{a^2-x^2}} = \sin^{-1} \frac{x}{a} + C$  or use substit.

$$x = 3 \sin u$$

$$a=3$$

$$\textcircled{\ominus} 2 \lim_{c \rightarrow 3^-} \sin^{-1} \frac{x}{3} \Big|_0^c = 2 \lim_{c \rightarrow 3^-} \left( \sin^{-1} \frac{c}{3} - \sin^{-1} 0 \right)$$

$$= 2 \cdot \left( \frac{\pi}{2} - 0 \right) = \pi : \text{improper } \int \text{ converges}$$

|  
finite

$$c \rightarrow 3^- \Rightarrow \frac{c}{3} \rightarrow \frac{3}{3} = 1$$

$$\sin^{-1}(1) = \frac{\pi}{2}$$

2/21/2014

## 8.8 Introduction to Differential Equations

Math 310 - ordinary differential equations

Math 480 - partial differential equations

Natural phenomena involve changes in time or/and in space, and they can be described or modeled by differential equations

$$x = f(t)$$

$t$ : independent variable

$x$ : dependent variable

$$f'(t) = \frac{df}{dt} : \text{rate of change of } f \text{ with respect to } t$$

Def a differential equation (DE) is an equation that involves an unknown function and at least one of its derivatives

Ex

$$\frac{dx}{dt} = x + \sin t$$

$$x = x(t)$$

this is a DE of the 1st order  
↑ 1st order derivative

Def The order of DE is the order of the highest derivative in the equation





Ex  $\frac{dx}{dt} = x + \sin t$  : linear 1<sup>st</sup> order DE

$\left(\frac{dx}{dt}\right)^1$   $\uparrow$   $x^1$

Aside:

$2x + 5$  : linear

$\ln x + x$  : nonlinear

$x^2 + e^x$  : nonlinear

Ex  $\frac{d^2y}{dx^2} - 3\frac{dy}{dx} + 2y = e^{2x}$  : linear 2<sup>nd</sup> order DE

$\underbrace{\hspace{10em}}_{R(x)}$

$a_2 = 1$      $a_1 = -3$      $a_0 = 2$

Ex  $2x \frac{dy}{dx} + e^x y = 5$  : 1<sup>st</sup> order linear DE

$\underbrace{\hspace{10em}}_{R(x)}$

$a_1 = 2x$      $a_0 = e^x$

Ex  $y \frac{dy}{dx} + 5 = e^x$  : nonlinear DE  
1<sup>st</sup> order

$y \frac{dy}{dx} = e^x - 5$

nonlinear term

Algebra problem: solve  $x^2 = 4$ . Solution is

$x = \pm 2$ . When we substitute  $x = \pm 2$  into algebraic equation  $x^2 = 4$ , i.e.  $(\pm 2)^2 = 4$  we get an identity  $4 \equiv 4$ .



Def To solve a DE, we need to find a function  $y = y(x)$  that when substituted into the DE produces an identity for all  $x$  from some interval  $I$  (and may satisfy other conditions - more later).

Ex  $y(x) = Ce^{x^2}$ ,  $C$  is an arbitrary const

$$\frac{dy}{dx} = \underbrace{Ce^{x^2}}_y \cdot 2x \Rightarrow \frac{dy}{dx} = 2xy : \begin{matrix} \text{1st order} \\ \text{DE} \end{matrix}$$

and  $y(x) = Ce^{x^2}$  is a solution of

$$\frac{dy}{dx} = 2xy$$

Check:

$$\underbrace{Ce^{x^2} \cdot 2x}_{\frac{dy}{dx}} = 2x \cdot \underbrace{Ce^{x^2}}_y \quad \checkmark \text{ identity for all } -\infty < x < \infty$$

$y(x) = Ce^{x^2}$ : one-parameter family of solutions

Note 1st order DEs have general solutions that depend on one arbitrary constant



$n^{\text{th}}$  order DEs have general solutions that depend on  $n$  arbitrary constants

### Ex Population Model

Time rate of change of population size  $P(t)$  is proportional to population size itself.

$P(t)$ : population size

$$\frac{dP}{dt} = kP$$

time rate of change of  $P$       proportional       $k > 0$ : const  
1st order DE

Solution:  $P(t) = C e^{kt}$ ,  $C$  is an arbitrary const

Check:

$$\frac{dP}{dt} = kP$$

$$\underbrace{C \cdot k \cdot e^{kt}}_{\frac{dP}{dt}} = k \cdot \underbrace{C e^{kt}}_P \quad \checkmark$$

$$\frac{dt}{P} \quad | \quad \frac{dP}{dt} = kP: \quad \underline{\text{separable DE}}$$

$$P \neq 0 \quad \underbrace{\frac{dP}{P}}_{\text{function of } P} = \underbrace{k dt}_{\text{function of } t}$$

$$\int \frac{dP}{P} = \int k dt$$

$$\text{exp} \quad \left| \ln |P| = kt + \tilde{C} \right.$$

$$e^{\ln |P|} = e^{kt + \tilde{C}}$$

$$e^{\ln |P|} = e^{kt} \cdot e^{\tilde{C}}$$

$$|P| = e^{kt} \cdot e^{\tilde{C}}$$

$P(t) = C e^{kt}$  : the general solution of

$$\frac{dP}{dt} = kP$$

The above method is called separation of variables.

2/24/2014

## Intro to Differential Equations (Cont'd)

Def A differential equation  $\frac{dy}{dt} = f(y)$  has a constant solution  $y(t) \equiv c$  if and only if  $f(c) = 0$ . In this case, the constant  $c$  is called an equilibrium solution of DE  $y' = f(y)$ .

Ex  $y' = \underbrace{y}_{f(y)}$  has one equilibrium solution  $y \equiv 0$  or  $y \equiv c = 0$

Ex  $y' = \underbrace{y^2 - 1}_{f(y)}$  has two equil. solutions  $c = \pm 1$  or  $y = \pm 1$

Def An equilibrium solution  $c$  is stable if  $y(t) \rightarrow c$  as  $t \rightarrow \infty$  for all nearby solutions  $y(t)$ . Otherwise, an equilibrium solution is unstable.

Ex Population model

$y' = \underbrace{ky}_{f(y)}$   $k \neq 0$  has 1 equil. solution  $y \equiv 0$



Last time we solved this equation and got the solution

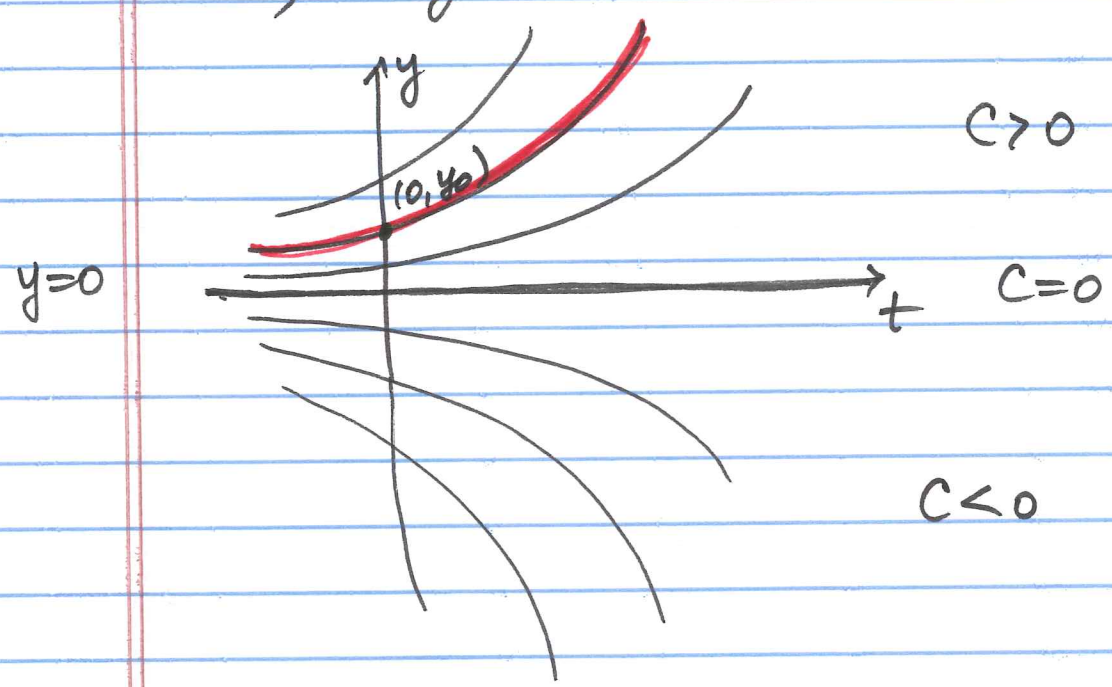
$$y(t) = Ce^{kt}, \quad C \text{ is arbitrary constant}$$

Let  $y(0) = y_0$ : initial condition

$$\text{at } t=0: \quad y_0 = \underbrace{C}_{=} e^{k \cdot 0} \Rightarrow C = y_0$$

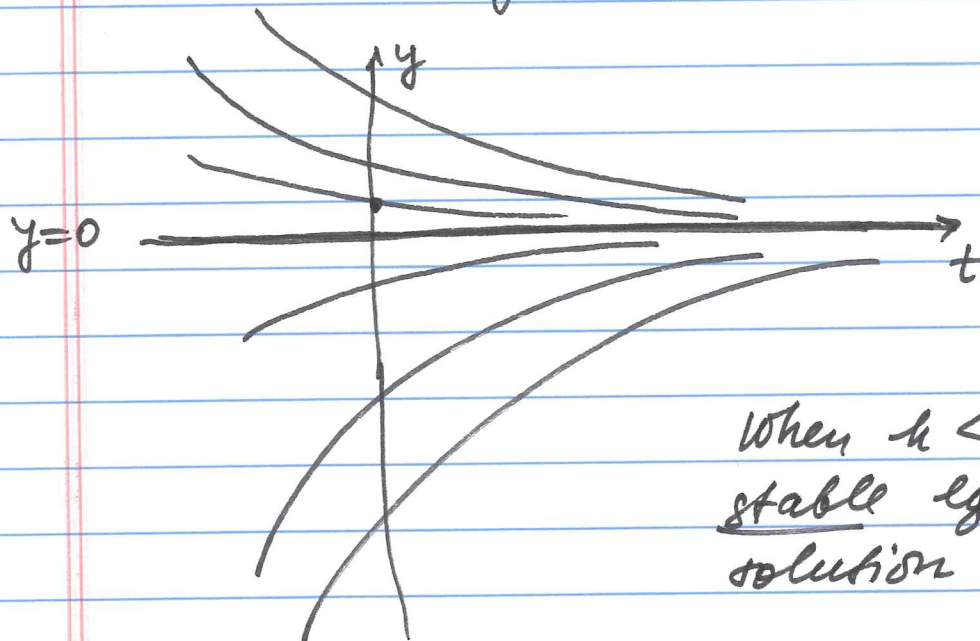
$\therefore y(t) = y_0 e^{kt}$ : particular solution

Let  $k > 0$ ,  $y(t) = Ce^{kt}$



$y=0$  is an unstable equilibrium solution.

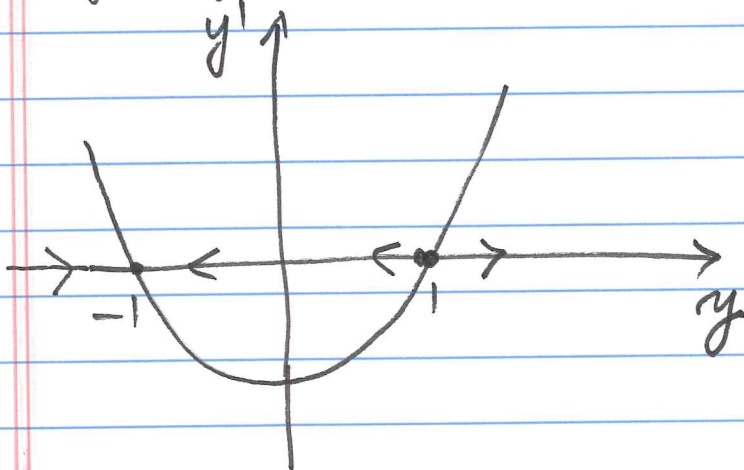
Let  $k < 0$ .  $y(t) = Ce^{kt}$



When  $k < 0$ ,  $y \equiv 0$  is stable equilibrium solution

Ex  $y' = y^2 - 1$  :  $y = \pm 1$

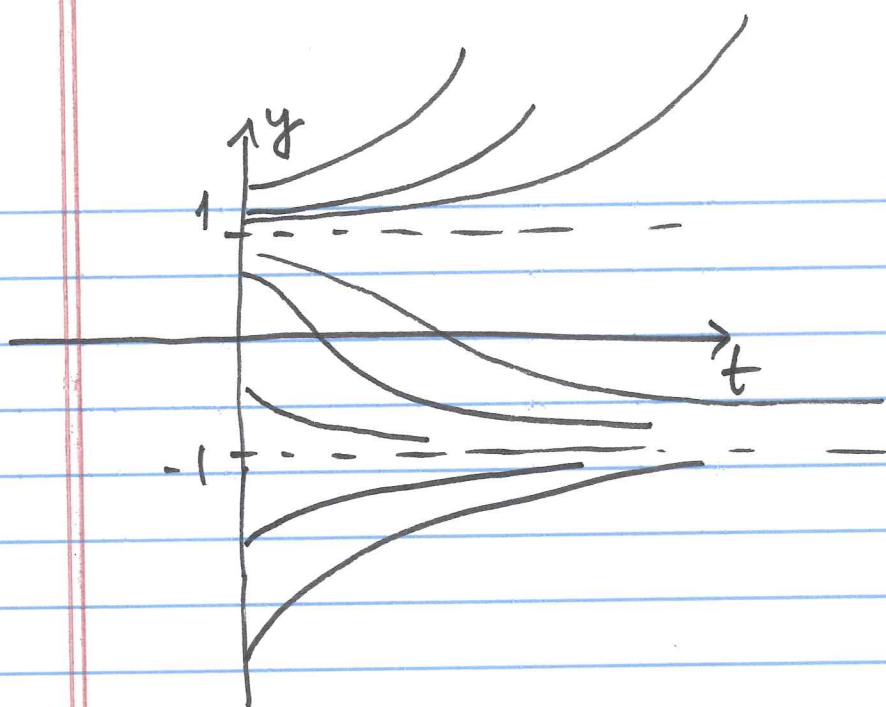
phase plane



phase plane: graphs  $y'$  as a function of  $y$

$y = -1$  is stable equil. solution

$y = 1$  is unstable equil. solution



$y=1$  is unstable  
equil. sol<sup>n</sup>

$y=-1$  is  
stable  
equil. sol<sup>n</sup>

ex

$P(t)$ : population size

$M$ : population threshold or maximum, population size that environment can support or carrying capacity of environment (due to limited resources),  $M > 0$

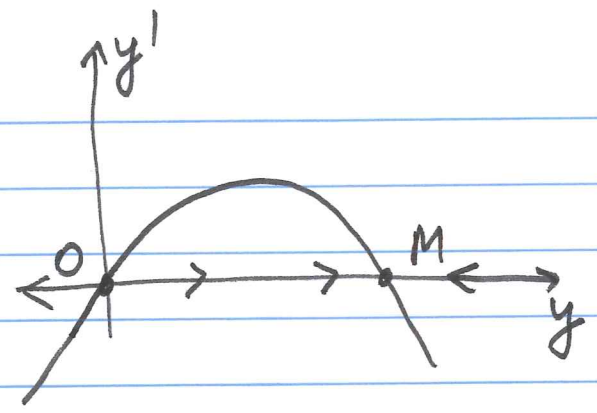
$$\frac{dP}{dt} = \underbrace{k(M-P)P}_{\text{variable growth rate}}, \quad k > 0 : \text{logistic equation}$$

$$f(P) = k(M-P)P \quad \text{or} \quad f(y) = k(M-y)y$$

$y=0, y=M$ : two equil. solutions

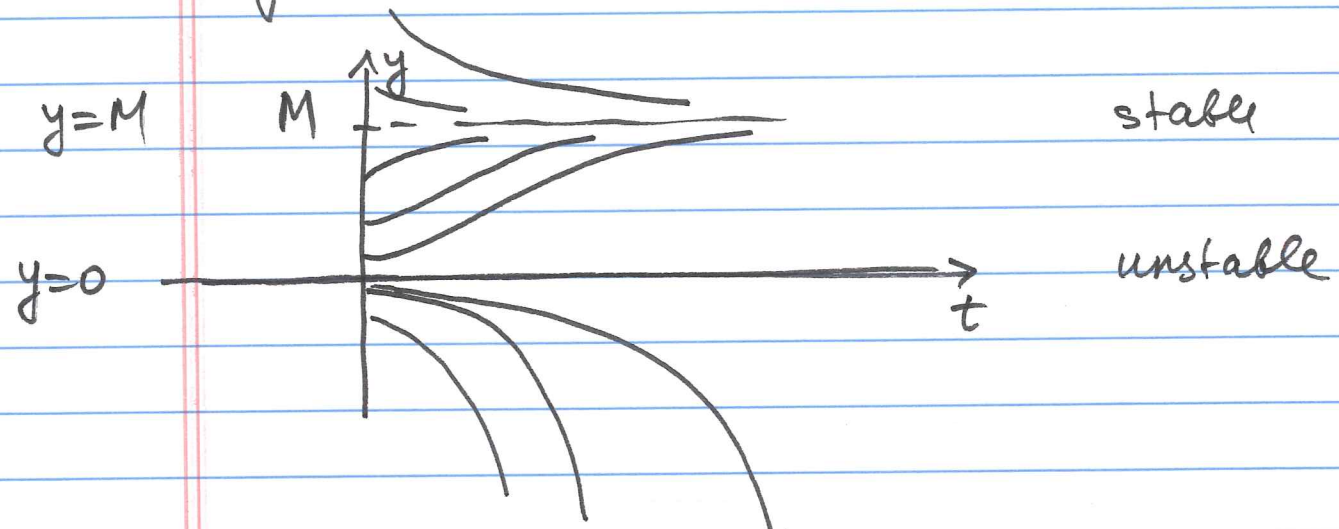


phase plane



$y=0$  is unstable equil. solution

$y=M$  is stable —||—



Solution of  $\frac{dP}{dt} = k(M-P)P$ : separable DE

$$\frac{dP}{(M-P)P} = k dt$$

$$\int \frac{dP}{(M-P)P} = \int k dt$$

$$\frac{1}{(M-P)P} = \frac{1}{M} \left( \frac{1}{M-P} + \frac{1}{P} \right): \text{partial fraction decomposition}$$

After some algebra we can get

$$P(t) = \frac{MP_0}{P_0 + (M - P_0)e^{-kMt}}$$

where  $P_0 = P(0)$ : initial population size

Q What is  $P(t)$  if  $P_0 = 0$ ?  $\Rightarrow P(t) = 0$   
 if  $P_0 = M$ ?  $\Rightarrow P(t) = M$   
 for all  $t$

This confirms that  $P(t) = 0$   
 and  $P(t) = M$  are equilibrium solutions.

Q if  $0 < P_0 < M$

$\lim_{t \rightarrow \infty} P(t) = ?$

$$\lim_{t \rightarrow \infty} \frac{MP_0}{P_0 + (M - P_0)e^{-kMt}} = M$$

$\therefore P(t) = M$  is stable  <sup>$\rightarrow 0$</sup>  equil. solution  
 and  $P(t) = 0$  is unstable  $\leftarrow$

This confirms what we knew from stability analysis.

Ex logistic equation with harvesting

$$\frac{dx}{dt} = kx(M-x) - h, \quad h > 0: \text{parameter}$$

$h=0$ : logistic equation

Ex  $\frac{dx}{dt} = x(4-x) - h$   $k=1$   
 $M=4$

$x(t)$ : population size (measured in hundreds)

$M=4, h=0 \Rightarrow \lim_{t \rightarrow \infty} x(t) = 4$  (hundred fish)

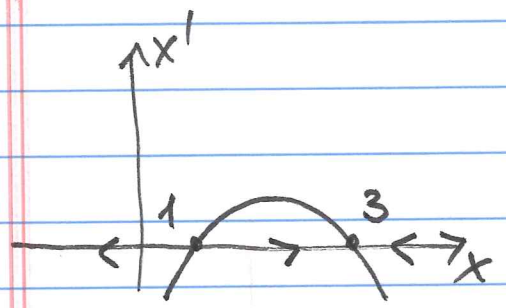
let  $h=3$

$$\frac{dx}{dt} = x(4-x) - 3$$

$$\frac{dx}{dt} = -(x^2 - 4x + 3)$$

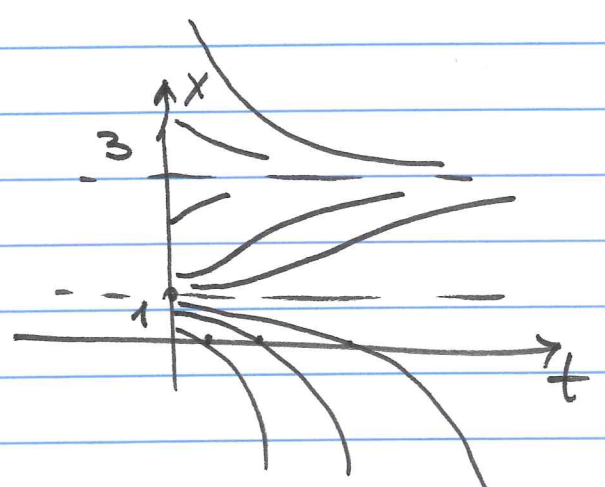
1, 3: roots

$$\frac{dx}{dt} = -(x-1)(x-3)$$



$x=1$ : unstable

$x=3$ : stable



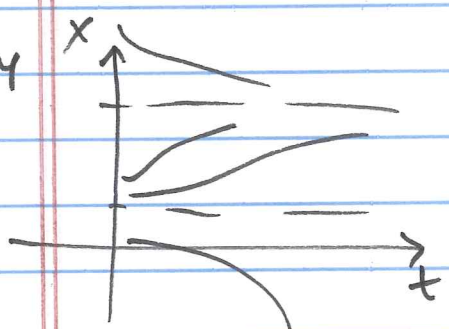
3 (hundred) fish is a new limiting population size



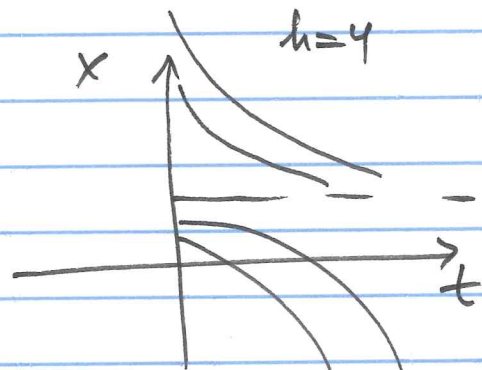
If lake is stocked initially with more than 100 fish, then  $x(t) \rightarrow 300$  fish as  $t \rightarrow \infty$ .

If lake is stocked initially w/ fewer than 100 fish, then lake will be "fished out" within finite time.

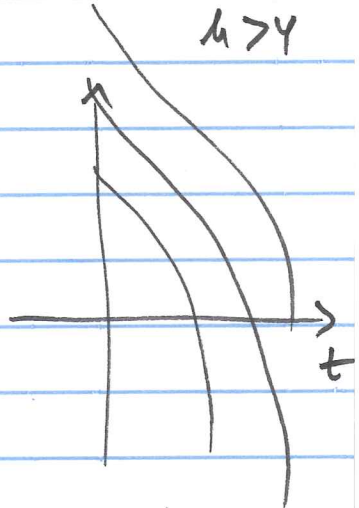
$h < 4$



new limiting population size



semi-stable equil. solution



extinction in a finite time

2/25/2014

## 8.8 Slope Fields and (Cont'd) Solution Curves

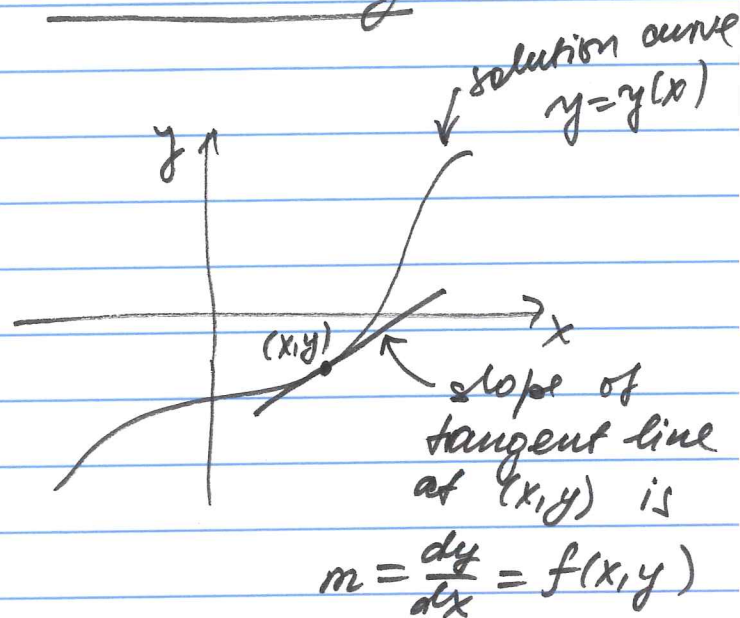
Consider a differential equation of the 1st order

$$\frac{dy}{dx} = f(x, y)$$

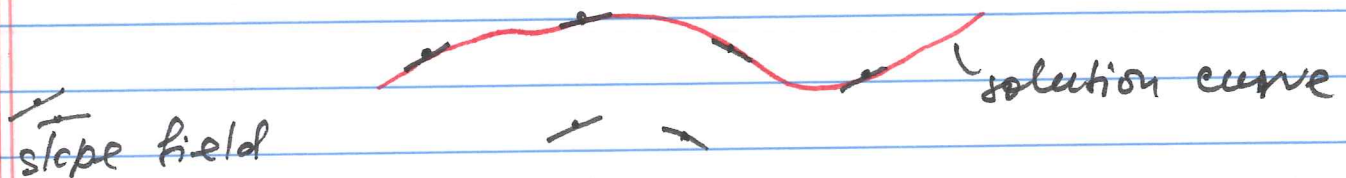
In general, it is not possible to find solution  $y(x)$  explicitly. But this solution can be approximated numerically or graphically.

$y = y(x)$ : solution

Solution curve is a graph of a solution



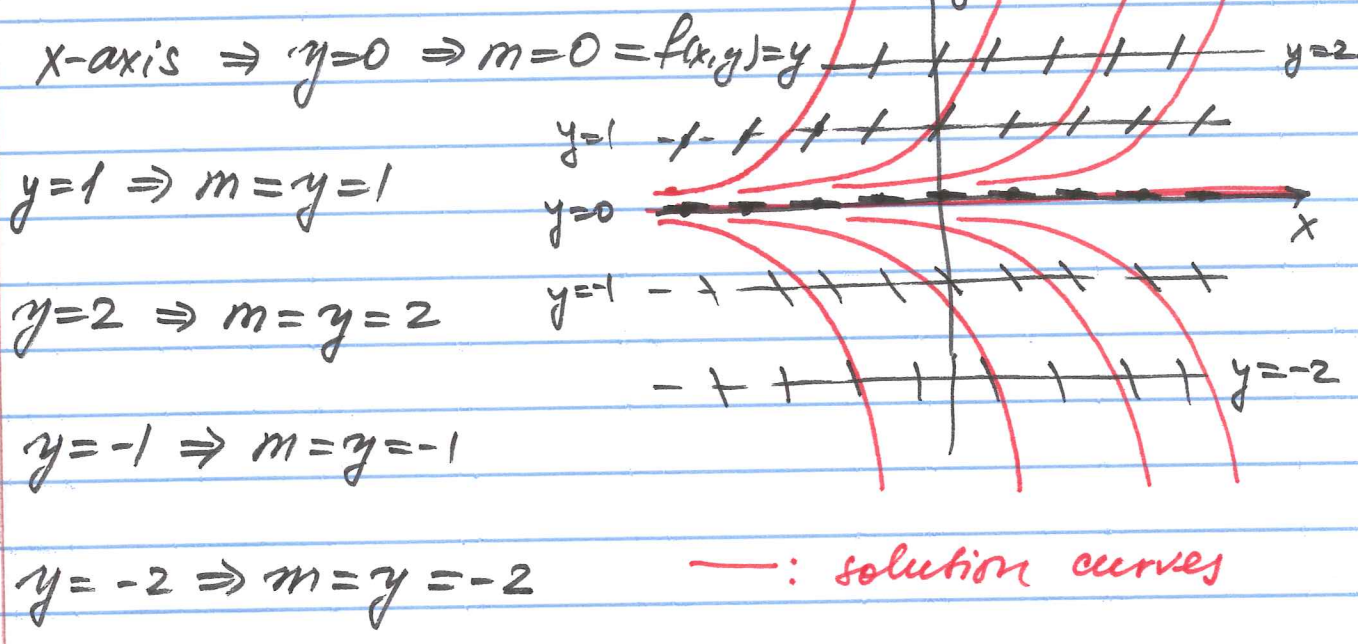
At every pt  $(x, y)$  we draw a small segment whose slope is  $f(x, y)$ . The collection of all such segments is slope field or direction field. Solution curve is tangent to these segments at all pts  $(x, y)$ .





Ex  $\frac{dy}{dx} = ky, \quad k=1$

$\Rightarrow \frac{dy}{dx} = y \Rightarrow \text{slope } m|_{(x,y)} = f(x,y) = y$



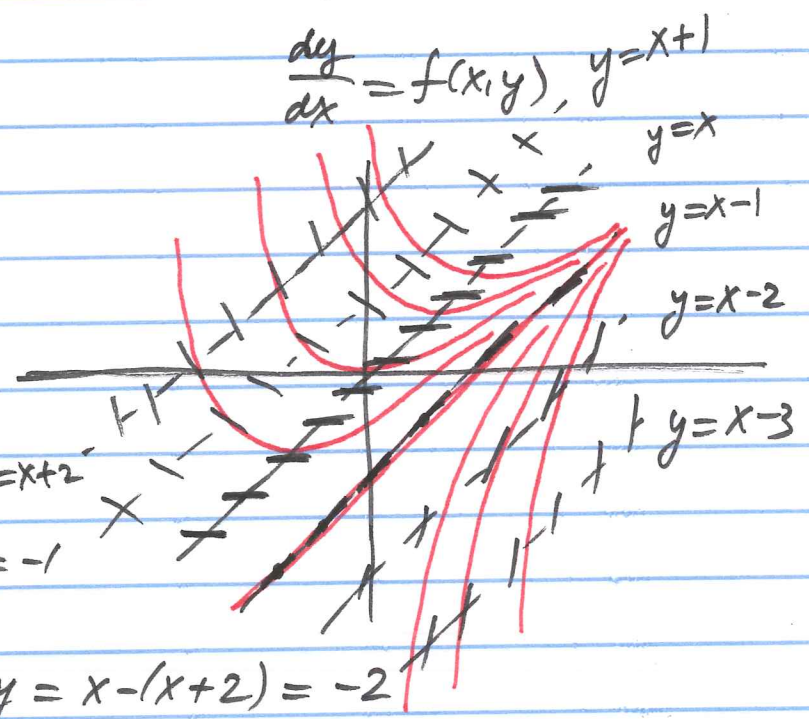
Ex  $\frac{dy}{dx} = x - y$   
 $f(x,y) = m$

Let  $y=x \Rightarrow m = x - y = 0$

Let  $y = x + 1 \Rightarrow m = x - y = x - (x + 1) = -1$

$y = x + 2 \Rightarrow m = x - y = x - (x + 2) = -2$

$y = x - 1 \Rightarrow m = x - (x - 1) = 1$





$$y = x - 2 \Rightarrow m = 2$$

Note:  $y = x - 1$  is a solution of  $\frac{dy}{dx} = x - y$   
 Indeed,

$$\frac{dy}{dx} = 1, \quad x - y = x - (x - 1) = 1$$

$$\Rightarrow \frac{dy}{dx} = x - y \quad \checkmark$$

$$\frac{dy}{dx} = kx(M - x)$$

## 9. Sequences and Infinite Series

### 9.1. An Overview

Consider a list of numbers:

$\{1, 4, 7, 10, 13, 16, \dots\}$  : a sequence

$\{a_1, a_2, a_3, \dots, a_n, \dots\}$  or  $\{a_n\}_{n=1}^{\infty}$  or  $\{a_n\}$

$a_n$ :  $n^{\text{th}}$  term

$n$ : index, usually  $n=0$  or  $n=1$

In this example, we can write

$$a_{n+1} = a_n + 3 \quad : \quad \text{recurrence relation or} \\
a_1 = 1 \quad \quad \quad n=1, 2, \dots \quad \text{implicit formula}$$

Another way:

$$a_1 = 1 = 1 + 3 \cdot 0$$

$$a_2 = 4 = 1 + 3 \cdot 1$$

$$a_3 = 7 = 1 + 3 \cdot 2$$

...

$$a_n = 1 + 3 \cdot (n-1) = 3n - 2, \quad n=1, 2, \dots$$

$$a_n = 3n - 2, \quad n=1, 2, \dots \quad : \quad \underline{\text{explicit formula}}$$

Def a sequence  $\{a_n\}$  is an ordered list of numbers of the form

$$\{a_1, a_2, \dots, a_n, \dots\}$$

A sequence may be generated by a recurrence formula of the form

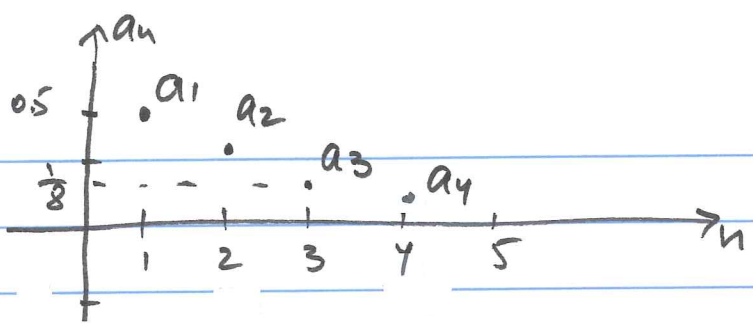
$$a_{n+1} = f(a_n) \quad \text{with } a_1 \text{ given, or by}$$

explicit formula for  $n^{\text{th}}$  term:

$$a_n = f(n), \quad n=1, 2, \dots$$

Ex  $a_n = \frac{1}{2^n} : \text{explicit}$

$$a_1 = \frac{1}{2^1}, \quad a_2 = \frac{1}{2^2} = \frac{1}{4}, \quad a_3 = \frac{1}{2^3} = \frac{1}{8}, \quad \dots$$



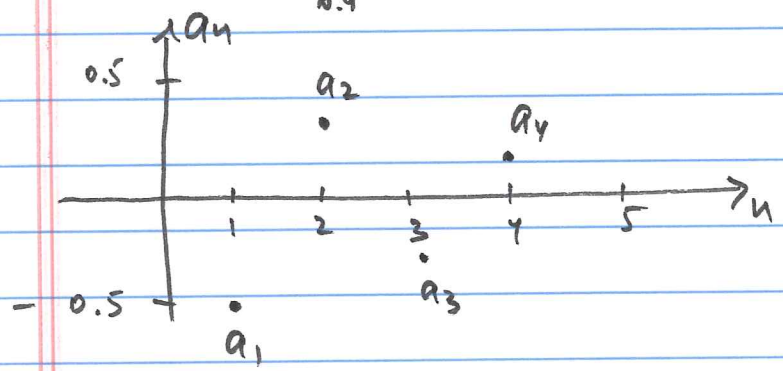
$a_n \rightarrow 0$  as  $n \rightarrow \infty$

Ex

$$a_n = \frac{(-1)^n n}{n^2 + 1}$$

$$\left\{ \frac{-1 \cdot 1}{1^2 + 1}, \frac{2}{2^2 + 1}, \frac{-3}{3^2 + 1}, \dots \right\}$$

$$\left\{ -\frac{1}{2}, \frac{2}{5}, \frac{-3}{10}, \frac{4}{17}, \dots \right\}$$



$a_n \rightarrow 0$  as  $n \rightarrow \infty$

Ex

$$\{b_n\} = \{3, 6, 12, 24, \dots\}$$

$\begin{matrix} \curvearrowright & \curvearrowright \\ \times 2 & \times 2 \end{matrix}$

$$b_{n+1} = 2b_n, \quad b_0 = 3$$

or

$$b_n = 3 \cdot 2^n, \quad n = 0, 1, 2, \dots$$