

$$\hat{i} \times \hat{j} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix} = \hat{i} \cdot 0 - \hat{j} \cdot 0 + \hat{k} \cdot 1 = \hat{k}$$

 $\hat{i}, \hat{j}, \hat{k}$

$$\boxed{\hat{k} \times \hat{i} = \hat{j}}$$

$$\boxed{\hat{j} \times \hat{k} = \hat{i}}$$

Similarly

$$\text{Note: } \hat{j} \times \hat{i} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{vmatrix} = \hat{i} \cdot 0 - \hat{j} \cdot 0 + \hat{k} \cdot (-1) = -\hat{k}$$

$$\Rightarrow \vec{a} \times \vec{b} \neq \vec{b} \times \vec{a} \quad \text{but} \quad \vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

$$\text{Note } \left. \begin{aligned} \hat{i} \times (\hat{i} \times \hat{j}) &= \hat{i} \times \hat{k} = -\hat{j} \\ (\hat{i} \times \hat{i}) \times \hat{j} &= \vec{0} \times \hat{j} = \vec{0} \end{aligned} \right\} \Rightarrow (\vec{a} \times \vec{b}) \times \vec{c} \neq \vec{a} \times (\vec{b} \times \vec{c})$$

Properties of Cross Product

$\vec{a}, \vec{b}, \vec{c}$: vectors; k : scalar

$$1. \vec{a} \times \vec{b} = -\vec{b} \times \vec{a}$$

$$2. (k\vec{a}) \times \vec{b} = k(\vec{a} \times \vec{b})$$

$$3. \vec{a} \times (\vec{b} + \vec{c}) = \vec{a} \times \vec{b} + \vec{a} \times \vec{c}$$

$$4. (\vec{a} + \vec{b}) \times \vec{c} = \vec{a} \times \vec{c} + \vec{b} \times \vec{c}$$

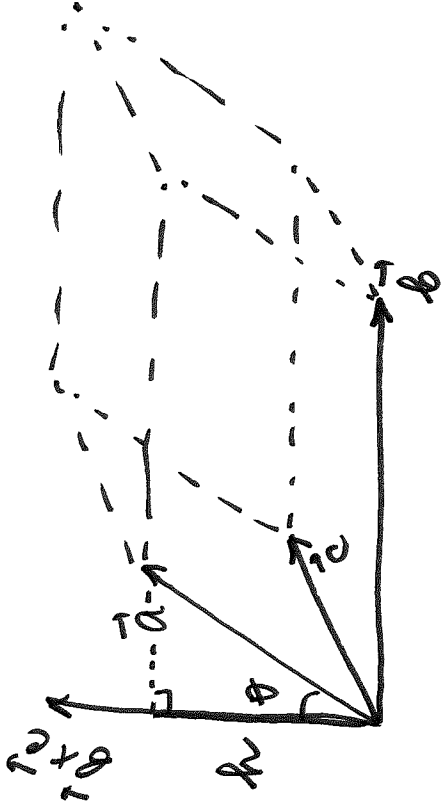
$$5. \vec{a} \cdot (\vec{b} \times \vec{c}) = (\vec{a} \times \vec{b}) \cdot \vec{c} : \text{triple scalar product}$$

$$6. \vec{a} \times (\vec{b} \times \vec{c}) = (\vec{a} \cdot \vec{c})\vec{b} - (\vec{a} \cdot \vec{b})\vec{c}$$

Geometric interpretation of triple scalar product

Recall

$$\vec{a} \cdot (\vec{b} \times \vec{c}) = \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \\ c_1 & c_2 & c_3 \end{vmatrix}$$



Goal: find volume of
parallelepiped

θ : angle between \vec{a} and $\vec{b} \times \vec{c}$

Volume = height \cdot area of base

$$\text{Area of base} = |\vec{b} \times \vec{c}|$$

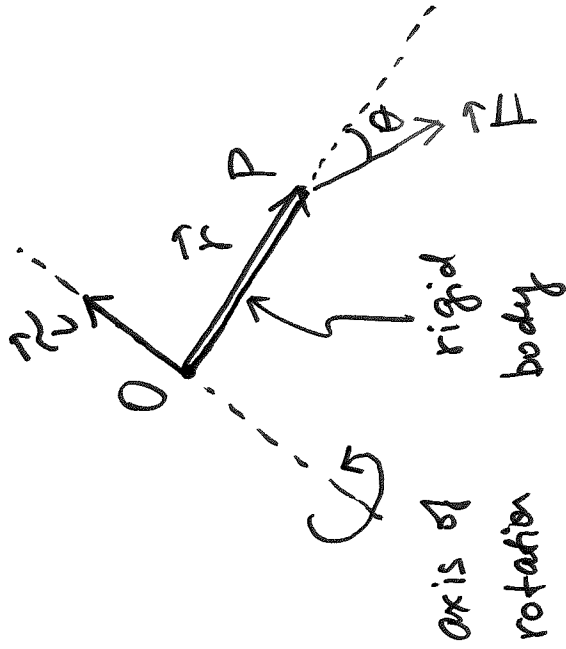
$$\text{height } h = |\vec{a}| \cdot |\cos \theta|$$

$$\therefore \text{Volume} = |\vec{a}| \cdot |\cos \theta| \cdot |\vec{b} \times \vec{c}| = |\vec{a}| \cdot |\vec{b} \times \vec{c}| \cdot |\cos \theta| = |\vec{a} \cdot (\vec{b} \times \vec{c})|$$

$$\Rightarrow \text{Volume} = |\vec{a} \cdot (\vec{b} \times \vec{c})|$$

Note: if $\vec{a} \cdot (\vec{b} \times \vec{c}) = 0 \Rightarrow \vec{a}, \vec{b}, \vec{c}$ are in the same plane
 \Rightarrow they are called coplanar vectors

Torque



$\vec{r} = \vec{OP}$: position vector
 Force \vec{F} acts on a rigid body
 at some pt P given by
 the position vector \vec{OP}

$\vec{\tau}$ (relative to origin) is

Torque

$$\vec{\tau} = \vec{r} \times \vec{F}$$

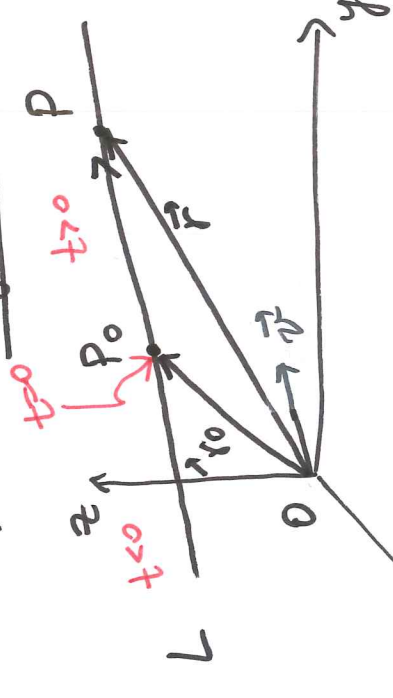
Torque measures tendency of a rigid body to rotate about the origin.

θ : angle between \vec{r} and \vec{F}
 $0 \leq \theta \leq \pi$

$$|\vec{\tau}| = |\vec{r} \times \vec{F}| = |\vec{r}| \cdot |\vec{F}| \cdot \sin \theta$$

magnitude of torque

12.5 Equations of Lines and Planes



a line is determined by a pt $P_0(x_0, y_0, z_0)$ and direction given by vector \vec{v} .
 L: line $L \parallel \vec{v}$

$P(x, y, z)$

Let $\vec{r}_0 = \vec{OP}_0$, $\vec{r} = \vec{OP}$

From Δ law: $\vec{OP}_0 + \vec{P}_0P = \vec{OP} \Rightarrow \vec{r} = \vec{r}_0 + \vec{P}_0P$

$\vec{P}_0P \parallel \vec{v} \Rightarrow \vec{P}_0P = t \cdot \vec{v}$ (scalar)

$\Rightarrow \vec{r} = \vec{r}_0 + \vec{P}_0P = \vec{r}_0 + t\vec{v} \Rightarrow$

vector eqⁿ of the line through pt P_0 in direction of vector \vec{v}

$\vec{r} = \vec{r}_0 + t\vec{v}$

$-\infty < t < \infty$

Let $\vec{v} = \langle a, b, c \rangle$

$P_0(x_0, y_0, z_0) \Rightarrow \vec{OP}_0 = \vec{r}_0 = \langle x_0, y_0, z_0 \rangle$

$P(x, y, z) \Rightarrow \vec{OP} = \vec{r} = \langle x, y, z \rangle$

line $L: \vec{r} = \vec{r}_0 + t\vec{v}$

$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t \langle a, b, c \rangle$

$$\therefore \left\{ \begin{array}{l} x = x_0 + t \cdot a, \quad y = y_0 + t \cdot b, \quad z = z_0 + t \cdot c, \\ t \in \mathbb{R} \end{array} \right.$$

parametric equation of a line
through pt $P_0(x_0, y_0, z_0)$ in direction
of $\vec{v} = \langle a, b, c \rangle$

a, b, c : direction numbers of line L

Note line can be defined using a different from P_0 pt on L
and any other vector $\parallel \vec{v}$. Equation(s) will change but
the line will be the same.

e.g. $\vec{n}_1 = k\vec{v}$ = $k\langle a, b, c \rangle = \langle ka, kb, kc \rangle$
| some const | new direction numbers

$$\vec{n}_1 \parallel \vec{v}$$

line: $x = x_0 + t \cdot a, \quad y = y_0 + t \cdot b, \quad z = z_0 + t \cdot c$

We can eliminate parameter t :

$$x = x_0 + t \cdot a \quad \Rightarrow \quad t = \frac{x - x_0}{a}$$

$$y = y_0 + t \cdot b \quad \Rightarrow \quad t = \frac{y - y_0}{b}$$

$$z = z_0 + t \cdot c \quad \Rightarrow \quad t = \frac{z - z_0}{c}$$

$$\therefore \frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c}$$

$$a, b, c \neq 0$$

symmetric equations of
line through pt $P_0(x_0, y_0, z_0)$
in direction $\vec{v} = \langle a, b, c \rangle$

Note: if one of a, b, c is zero, we still can write symmetric equations

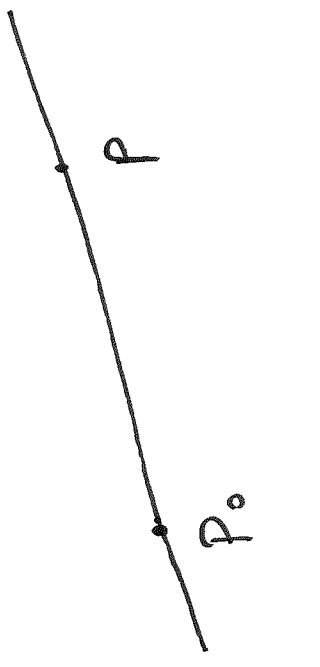
let $a=0 \Rightarrow x = x_0 + \cancel{at}^0 \Rightarrow \boxed{x = x_0}$

$b, c \neq 0 \Rightarrow \boxed{\frac{y-y_0}{b} = \frac{z-z_0}{c}}$

$\therefore \boxed{x = x_0, \frac{y-y_0}{b} = \frac{z-z_0}{c}}$

Geometrically: this line is in the plane parallel to yz -plane

Ex Find parametric and symmetric equations for the line through $(6, 1, -3)$ and $(2, 4, 5)$.



let $P_0(6, 1, -3), P(2, 4, 5)$
 $\vec{r} \parallel \vec{v}$ and we can take $\vec{v} = \vec{P_0P}$

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Note as pt P_0 we can choose either $(6, 1, -3)$ or $(2, 4, 5)$

$$P_0(6, 1, -3) \Rightarrow x_0 = 6, y_0 = 1, z_0 = -3$$

Parametric equations of the line

$$x = x_0 + ta, \quad y = y_0 + tb, \quad z = z_0 + tc$$

$$\vec{v} = \langle a, b, c \rangle = \vec{P_0P} = \langle 2-6, 4-1, 5-(-3) \rangle = \langle -4, 3, 8 \rangle$$

$$\Rightarrow a = -4, \quad b = 3, \quad c = 8$$

$$\therefore \boxed{x = 6 - 4 \cdot t, \quad y = 1 + 3t, \quad z = -3 + 8t, \quad t \in \mathbb{R}}$$

parametric eq^{ns}

of the line

$$\frac{x-x_0}{a} = \frac{y-y_0}{b} = \frac{z-z_0}{c}$$

$$\Rightarrow \boxed{\frac{x-6}{-4} = \frac{y-1}{3} = \frac{z+3}{8}}$$

symmetric eq^{ns} of the line