

System Analysis and Duhamel's Principle

Consider

$$ax'' + bx' + cx = f(t), \quad a, b, c: \text{const} \quad (1)$$

$f(t)$: input function

$x(t)$: output/response function and $F(s) = \mathcal{L}\{f(t)\}$

Let $x(0) = x'(0) = 0$. Let $X(s) = \mathcal{L}\{x(t)\}$. Then applying

Laplace transform to both sides of (1) we get

$$a(s^2 X(s) - s x'(0) - x'(0)) + b(s X(s) - x(0)) + c X(s) = F(s)$$

$$\Rightarrow (as^2 + bs + c) X(s) = F(s)$$

Laplace transform
of response

$$\Rightarrow X(s) = \frac{F(s)}{as^2 + bs + c} = \frac{1}{as^2 + bs + c} \cdot F(s) = \underbrace{W(s)}_{\equiv W(s)} \cdot F(s)$$

$$W(s) = \frac{1}{as^2 + bs + c} : \text{transfer function of system}$$

$$w(t) = \mathcal{L}^{-1}\{W(s)\} : \text{weight function of system or input response function (more - next page)}$$

$$X(s) = W(s) \cdot F(s) \Rightarrow$$

$$x(t) = w(t) * f(t) = \int_0^t w(\tau) f(t-\tau) d\tau$$

Duhamel's principle

Note

$$W(s) = \frac{1}{as^2 + bs + c} =$$

$$\frac{1}{as^2 + bs + c} \cdot 1 =$$

$$W(s) \cdot \mathcal{L}\{\delta(t)\}$$

Laplace transform of response due to input $f(t) = \delta(t)$

$\mathcal{L}\{\delta(t)\}$

$$\therefore w(t) = w(t) * \delta(t) = \int_0^t w(\tau) \delta(t-\tau) d\tau = w(t)$$

\therefore weight function $w(t)$ is response of system to delta function

$\delta(t) \Rightarrow w(t)$ is called the impulse response function

Let $f(t) = u(t)$: unit step function

$x(t) = h(t)$: response to $u(t)$ (it is easier to measure than response to $\delta(t)$)

$$X(s) = W(s) \cdot F(s) \quad \text{or} \quad x(t) = w(t) * f(t)$$

$$\therefore H(s) = \mathcal{L}\{h(t)\} = W(s) \cdot \mathcal{L}\{u(t)\} \quad \text{or} \quad h(t) = w(t) * u(t)$$

but $\mathcal{L}\{u(t)\} = \frac{1}{s} \Rightarrow H(s) = W(s) \cdot \frac{1}{s}$

and $h(t) = w(t) * u(t) = \int_0^t w(\tau) u(t-\tau) d\tau \Leftrightarrow$
 $0 \leq \tau \leq t \Rightarrow t-\tau \geq 0$

$$u(t-\tau) = \begin{cases} 1, & t-\tau \geq 0 \\ 0, & t-\tau < 0 \end{cases}$$

$$\Leftrightarrow \int_0^t w(\tau) \cdot 1 d\tau = \int_0^t w(\tau) d\tau \Rightarrow$$

$$h(t) = \int_0^t w(\tau) d\tau$$

$$\Rightarrow h'(t) = \frac{d}{dt} \int_0^t w(\tau) d\tau = w(t) \Rightarrow$$

$$w(t) = h'(t)$$

weight function or unit impulse response of unit step function is the derivative of unit step function response

Then response $x(t)$ (Duhamel's principle) can be written as

$$x(t) = w(t) * f(t) = \int_0^t w(\tau) f(t-\tau) d\tau = \int_0^t h'(t) f(t-\tau) d\tau$$

#6
S 7.5

$$F(s) = \frac{se^{-s}}{s^2 + \pi^2} = e^{-s} \cdot \frac{s}{s^2 + \pi^2}$$

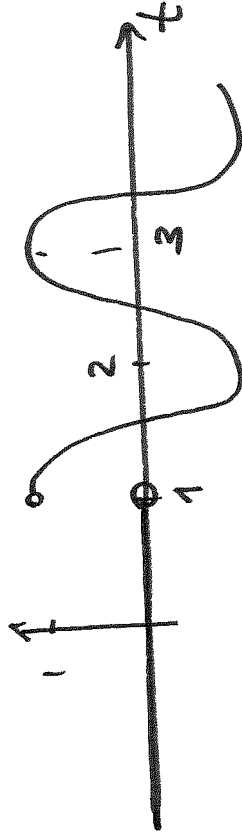
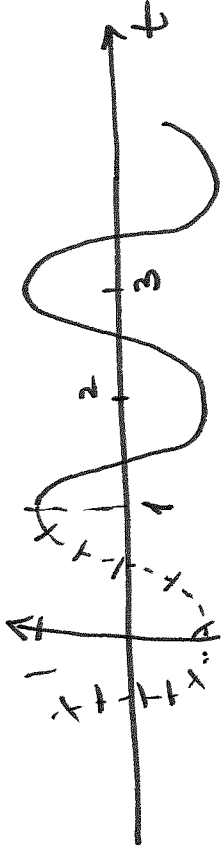
$$\mathcal{L}\{u(t-a)f(t-a)\} = e^{-as}F(s)$$

$$\begin{matrix} a=1 \\ t \rightarrow t-1 \end{matrix} \mathcal{L}\{\cos \pi t\}$$

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = \cos \frac{\pi(t-1)}{\pi t - \pi} \cdot u(t-1) = [\cos \pi t \cdot \underbrace{\cos(\pi)}_{-1} + \sin \pi t \cdot \underbrace{\sin(\pi)}_0] u(t-1) \equiv$$

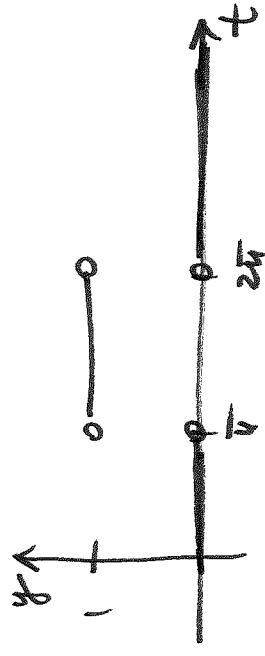
$$\cos(x-y) = \cos x \cos y + \sin x \sin y$$

$$\equiv -\cos \pi t \cdot u(t-1)$$



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S7.5

$$f(t) = \begin{cases} 0, & t < \pi \\ \sin 2t, & \pi \leq t \leq 2\pi \\ 0, & t > 2\pi \end{cases}$$

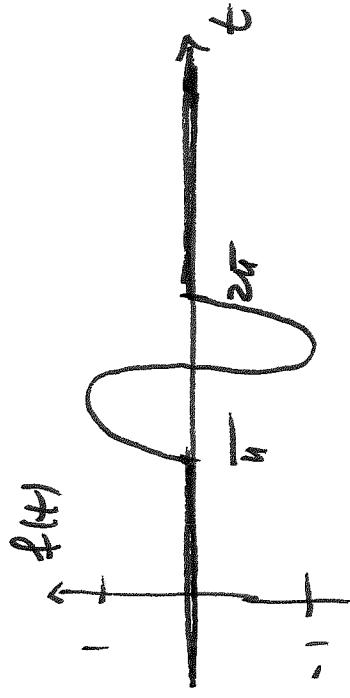


Find $\mathcal{L}\{f(t)\} = F(s)$

$$u(t-\pi) - u(t-2\pi)$$

$$\therefore f(t) = [u(t-\pi) - u(t-2\pi)] \cdot \sin 2t =$$

$$= u(t-\pi) \sin 2t - u(t-2\pi) \sin 2t \quad \boxed{=}$$



Shift-Loop Thm:

$$\mathcal{L}\{u(t-a)f(t-a)\} = e^{-as}F(s)$$

$$\sin 2t \stackrel{?}{=} \sin 2(t-\pi) = \sin(2t - 2\pi) = \sin 2t \quad \checkmark$$

by periodicity

$$\sin 2t \stackrel{?}{=} \sin 2(t-2\pi) = \sin(2t - 4\pi) = \sin 2t \quad \checkmark$$

by periodicity

$$\boxed{\equiv} \quad u(t-\pi) \sin 2(t-\pi) - u(t-2\pi) \sin 2(t-2\pi) = f(t)$$

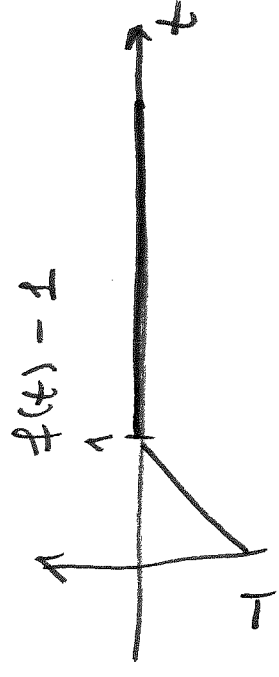
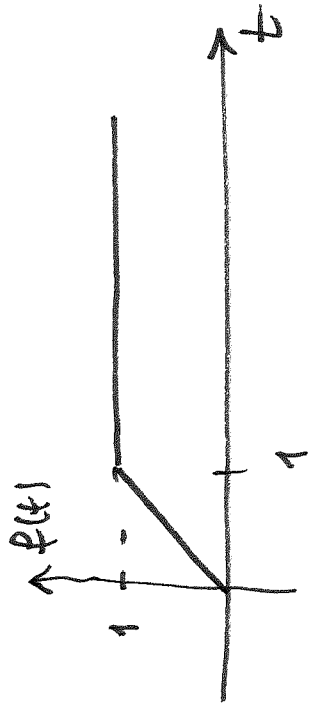
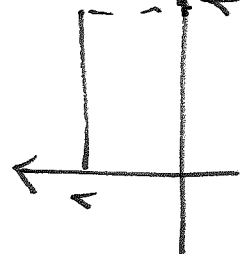
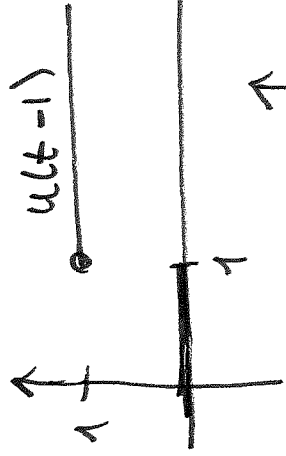
$$\therefore F(s) = \frac{2}{s^2+2^2} \cdot e^{-\pi s} - \frac{2}{s^2+2^2} \cdot e^{-2\pi s} = \frac{2}{s^2+4} (e^{-\pi s} - e^{-2\pi s})$$

Linearity

#20
S 7.5

$$f(t) = \begin{cases} t, & t \leq 1 \\ 1, & t > 1 \end{cases}$$

$$f(t) - 1 = \begin{cases} t-1, & t \leq 1 \\ 0, & t > 1 \end{cases}$$



\Downarrow

$$f(t) - 1 = [1 - u(t-1)] \cdot (t-1)$$

Then

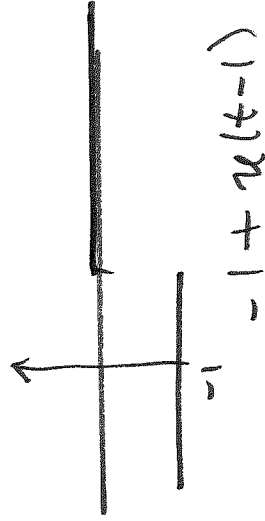
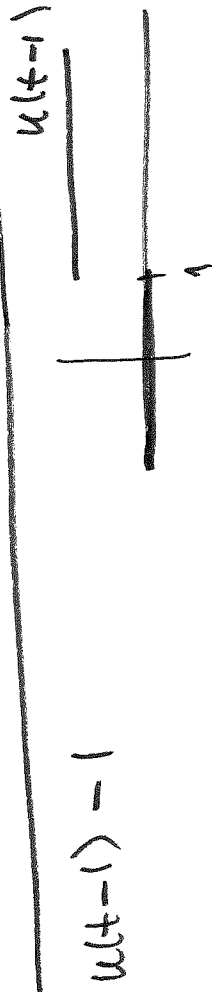
$$f(t) = [1 - u(t-1)](t-1) + 1 = t - 1 - u(t-1)(t-1) + 1$$

$$\Rightarrow f(t) = t - (t-1)u(t-1)$$

$$\mathcal{L}\{t^n\} = \frac{n!}{s^{n+1}}$$

$$\therefore F(s) = \frac{1}{s^2} - \frac{1}{s^2}e^{-s} = \frac{1}{s^2}(1 - e^{-s})$$

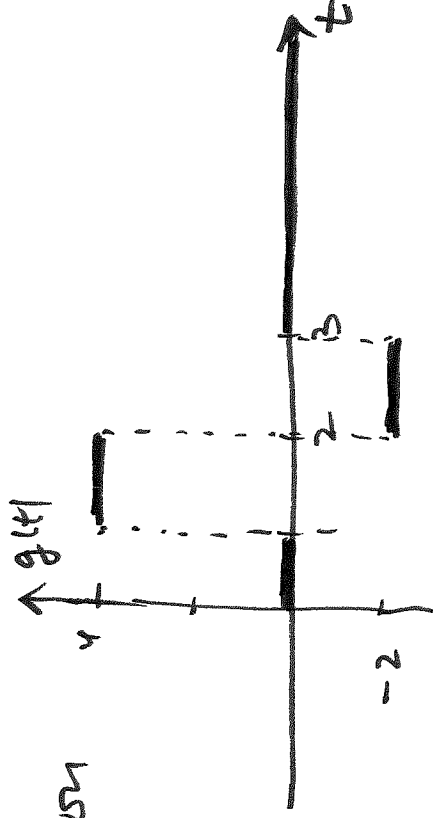
$$\mathcal{L}\{u(t-a)f(t-a)\} = e^{-as}F(s)$$



Ex Solve and graph the solution

$$y' + 2y = g(t), \quad y(0) = 6$$

$$\text{where } g(t) = \begin{cases} 0, & 0 < t < 1 \\ 4, & 1 < t < 2 \\ -2, & 2 < t < 3 \\ 0, & t > 3 \end{cases}$$



From the graph: $g(t) = 4u(t-1) - 6u(t-2) + 2u(t-3)$

$$\mathcal{L}\{g(t)\} = G(s) = 4 \frac{e^{-s}}{s} - 6 \frac{e^{-2s}}{s} + 2 \frac{e^{-3s}}{s} \quad \mathcal{L}\{u(t-a)\} = \frac{e^{-as}}{s}$$

Let $Y(s) = \mathcal{L}\{y(t)\}$. Applying Laplace transform to both sides

of DE, we get

$$sY(s) - y(0) + 2Y(s) = 4 \frac{e^{-s}}{s} - 6 \frac{e^{-2s}}{s} + 2 \frac{e^{-3s}}{s}$$

$$(s+2)Y(s) = 6 + 4 \frac{e^{-s}}{s} - 6 \frac{e^{-2s}}{s} + 2 \frac{e^{-3s}}{s}$$

$$Y(s) = \frac{6}{s+2} + e^{-s} \frac{4}{s(s+2)} + e^{-2s} \frac{(-6)}{s(s+2)} + e^{-3s} \frac{2}{s(s+2)}$$

$$\frac{4}{s(s+2)} = \frac{2}{s} - \frac{2}{s+2}$$

$$-\frac{6}{s(s+2)} = -\frac{3}{s} + \frac{3}{s+2}$$

$$\frac{2}{s(s+2)} = \frac{1}{s} - \frac{1}{s+2}$$

$$Y(s) = \frac{6}{s+2} + \left(\frac{2}{s} - \frac{2}{s+2}\right)e^{-s} + \left(-\frac{3}{s} + \frac{3}{s+2}\right)e^{-2s} +$$

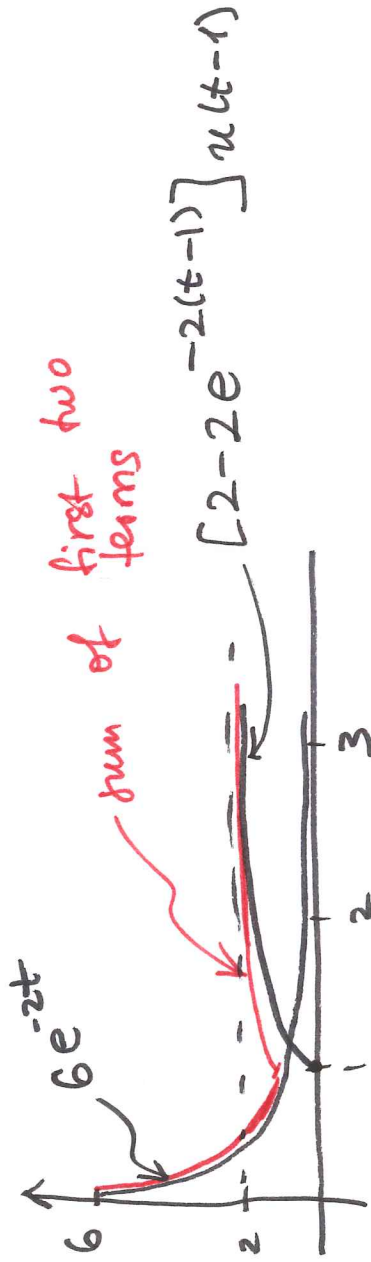
$$+ \left(\frac{1}{s} - \frac{1}{s+2}\right)e^{-3s}$$

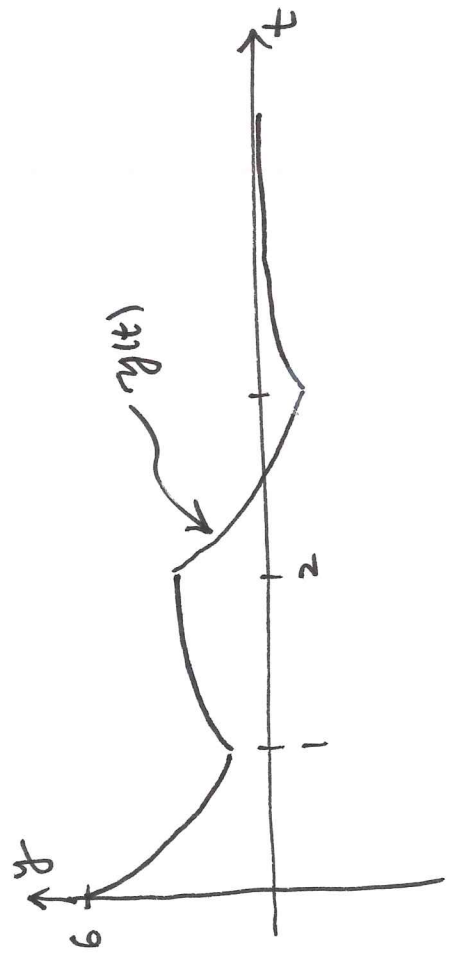
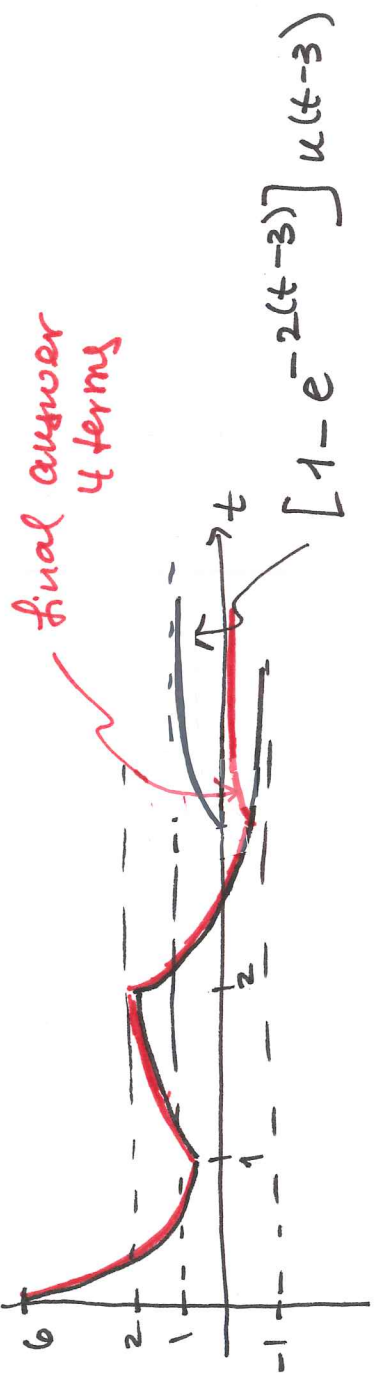
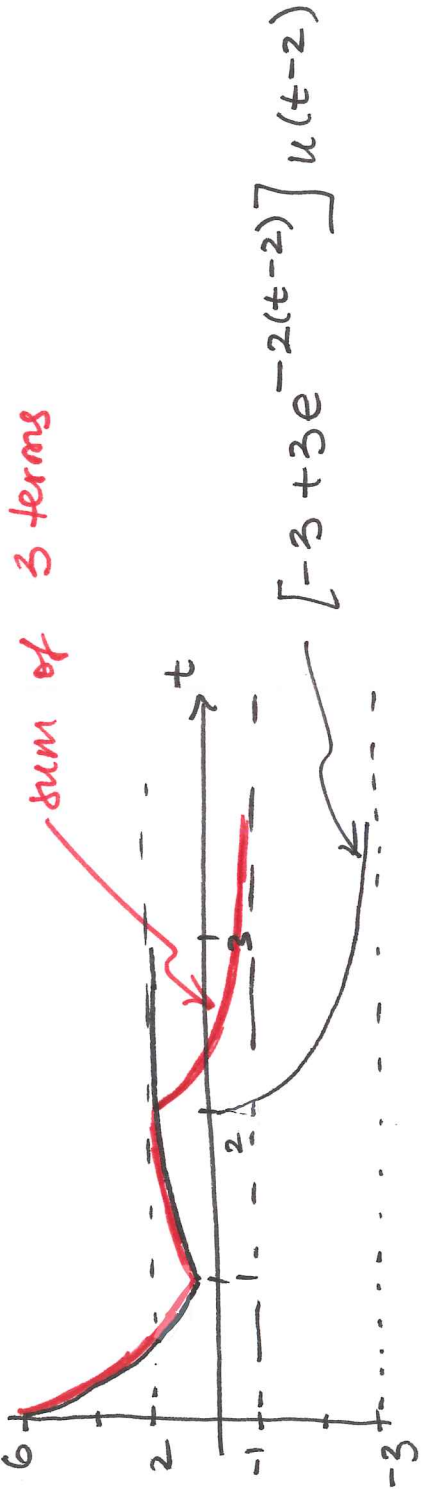
$$\mathcal{L}\{e^{at}\} = \frac{1}{s-a}$$

$$\mathcal{L}\{u(t-a)f(t-a)\} = e^{-as}F(s)$$

$$y(t) = 6e^{-2t} + [2 - 2e^{-2(t-1)}]u(t-1) +$$

$$+ [-3 + 3e^{-2(t-2)}]u(t-2) + [1 - e^{-2(t-3)}]u(t-3)$$





Math 310: Final Review (More problems)

#21
S1.4

$$2y \frac{dy}{dx} = \frac{x}{\sqrt{x^2-16}}, \quad y(5)=2$$

$$\frac{dy}{dx} = \frac{x}{2y\sqrt{x^2-16}} = \underbrace{\frac{1}{y}}_{f^2 \text{ of } y} \cdot \underbrace{\frac{x}{2\sqrt{x^2-16}}}_{f^2 \text{ of } x} \quad : \text{ separable ODE (1st order nonlinear)}$$

$$y \, dy = \frac{x \, dx}{2\sqrt{x^2-16}}$$

$$\int y \, dy = \int \frac{x \, dx}{2\sqrt{x^2-16}}$$

$$\frac{y^2}{2} = \frac{1}{2} \sqrt{x^2-16} + C \quad / \cdot 2$$

$$\int \frac{x \, dx}{2\sqrt{x^2-16}} = \left| \begin{array}{l} u = x^2-16 \\ du = 2x \, dx \end{array} \right| = \int \frac{du}{2 \cdot 2 \sqrt{u}} = \frac{1}{2} \sqrt{u} + C$$

$$= \frac{1}{2} \sqrt{x^2-16} + C$$

$$y^2 = \sqrt{x^2-16} + \tilde{C}$$

$$y(5)=2 \Rightarrow 2^2 = \sqrt{5^2-16} + \tilde{C}$$

$$4 = 3 + \tilde{C} \Rightarrow \tilde{C} = 1$$

$$\Rightarrow y^2 = \sqrt{x^2 - 16} + 1$$

$$y(5) = 2$$

$$y = \pm \sqrt{\sqrt{x^2 - 16} + 1}$$

choose "+" solution

$$\therefore \boxed{y = \sqrt{\sqrt{x^2 - 16} + 1}}$$

9
S1.5

$$xy' - y = x, \quad y(1) = 7$$

1st order linear DE

Multiply both sides
of DE by $\frac{1}{x}$.

$$y' + P(x)y = Q(x)$$

$$p(x) = e^{\int P(x) dx} \quad \text{: integrating factor}$$

$$\underbrace{y'}_p - \underbrace{\frac{1}{x}y}_Q = \frac{1}{x}$$

$$py = \int pQ dx + C$$

$$p(x) = e^{\int P(x) dx} = e^{\int (-\frac{1}{x}) dx} = e^{-\ln x} = e^{\ln x^{-1}} = \frac{1}{x}$$

$$py = \int pQ dx + C$$

$$e^{\ln a} = a$$

$$\frac{1}{x} \cdot y = \int \frac{1}{x} \cdot 1 dx + C$$

$$a \ln b = \ln b^a$$

$$\frac{1}{x} y = \ln x + C$$

$$\text{IC: } y(1) = 7 \Rightarrow \frac{1}{1} \cdot 7 = \ln 1 + C \Rightarrow \boxed{C = 7}$$

$$\frac{1}{x}y = \ln x + 7 \Rightarrow \boxed{y = x(\ln x + 7)}$$

Method of undetermined coefficients

#48

S 9.5

$$y'' - 2y' - 8y = 3e^{-2x} \quad (1)$$

$$(D^2 - 2D - 8)y = 3e^{-2x}$$

$$-2, 4 \quad -2 \quad A(D) = D + 2$$

$$(D + 2)(D - 4)y = 3e^{-2x}$$

Higher order DE is

$$[(D + 2)(D - 4)](D + 2)y = 0$$

$$-2, 4; -2$$

$$y(x) = C_1 e^{-2x} + C_2 e^{4x} + K_1 x e^{-2x}$$

$y_p = K_1 x e^{-2x}$: candidate for particular solution

Substitute y_p into (1) to find K_1

$$\textcircled{-8} \quad y_p = K_1 x e^{-2x}$$

$$\textcircled{-2} \quad y_p' = K_1 e^{-2x} + K_1 x (-2) e^{-2x} = K_1 e^{-2x} - 2K_1 x e^{-2x}$$

$$y_p'' = -2K_1 e^{-2x} - 2K_1 e^{-2x} + 4K_1 x e^{-2x}$$

① $y'' = -4K_1 e^{-2x} + 4K_1 x e^{-2x}$

$(-8K_1 - 2(-2)K_1 + 4K_1) x e^{-2x} + (-2K_1 - 4K_1) e^{-2x} = 3e^{-2x}$

$\{e^{-2x}, x e^{-2x}\}$: linear independent

$x e^{-2x}$: $-8K_1 + 4K_1 + 4K_1 = 0$ $-8K_1 + 8K_1 = 0$ ✓

e^{-2x} : $-6K_1 = 3 \Rightarrow K_1 = -\frac{1}{2}$

$\therefore y_p(x) = -\frac{1}{2} x e^{-2x}$

General solution is

$y(x) = C_1 e^{-2x} + C_2 e^{4x} - \frac{1}{2} x e^{-2x}$

Variation of parameters

#48
S3.5

$y'' - 2y' - 8y = 3e^{-2x}$

$y'' - 2y' - 8y = 0$: associated homogeneous eqⁿ

$(D^2 - 2D - 8)y = 0$

$(D+2)(D-4)y = 0 \Rightarrow y_e = C_1 e^{-2x} + C_2 e^{4x}$

Assume

$$y_p(x) = A_1(x)e^{-2x} + A_2(x)e^{4x}$$

To find A_1, A_2 , we solve for A_1', A_2' the following system of equations

$$\begin{cases} y_1 A_1' + y_2 A_2' = 0 \\ y_1' A_1' + y_2' A_2' = \frac{R(x)}{a_2(x)} \end{cases}$$

where y_1, y_2 are linearly independent solutions of the associated homogeneous DE, i.e.

$$y_1 = e^{-2x}, \quad y_2 = e^{4x}$$

$$R(x) = 3e^{-2x}, \quad a_2 = 1$$

$$\begin{pmatrix} e^{-2x} & e^{4x} \\ -2e^{-2x} & 4e^{4x} \end{pmatrix} \begin{pmatrix} A_1' \\ A_2' \end{pmatrix} = \begin{pmatrix} 0 \\ 3e^{-2x}/1 \end{pmatrix}$$

Solve using Cramer's rule

$$\begin{aligned} \Delta &= \begin{vmatrix} e^{-2x} & e^{4x} \\ -2e^{-2x} & 4e^{4x} \end{vmatrix} = 4e^{-2x}e^{4x} + 2e^{-2x}e^{4x} \\ &= 4e^{2x} + 2e^{2x} = 6e^{2x} \end{aligned}$$

$$\Delta_1 = \begin{vmatrix} 0 & e^{4x} \\ 3e^{-2x} & 4e^{4x} \end{vmatrix} = -3e^{2x}$$

$$\Delta_2 = \begin{vmatrix} e^{-2x} & 0 \\ -2e^{-2x} & 3e^{-2x} \end{vmatrix} = 3e^{-4x}$$

Then

$$A_1' = \frac{\Delta_1}{\Delta} = \frac{-3e^{2x}}{6e^{2x}} = -\frac{1}{2}$$

$$A_1(x) = \int \left(-\frac{1}{2}\right) dx = \boxed{-\frac{1}{2}x = A_1(x)}$$

$$A_2' = \frac{\Delta_2}{\Delta} = \frac{3e^{-4x}}{6e^{2x}} = \frac{1}{2}e^{-6x}$$

$$A_2(x) = \int \frac{1}{2}e^{-6x} dx = \boxed{-\frac{1}{12}e^{-6x} = A_2(x)}$$

Hence,

$$\begin{aligned} y_p(x) &= A_1 \cdot y_1 + A_2 \cdot y_2 = -\frac{1}{2}x \cdot e^{-2x} - \frac{1}{12}e^{-6x} \cdot e^{4x} \\ &= -\frac{1}{2}x e^{-2x} - \frac{1}{12}e^{-2x} \end{aligned}$$

Then, the general solution is

$$y(x) = \underbrace{C_1 e^{-2x} + C_2 e^{4x}}_{y_h} - \frac{1}{2}x e^{-2x} - \frac{1}{12}e^{-2x} \quad \textcircled{=}$$

$$\Rightarrow \tilde{C}_1 e^{-2x} + C_2 e^{yx} - \frac{1}{2} x e^{-2x} \quad \text{--- yp}$$

$$\tilde{C}_1 = C_1 - \frac{1}{2} \quad \text{: arbitrary constant}$$

\ arbitrary constant

#21

S7.4

$$f(t) = \frac{e^{3t} - 1}{t}$$

Thm: integration of transforms

$$\mathcal{L}\left\{ \frac{f(t)}{t} \right\} = \int_s^\infty F(\sigma) d\sigma \quad |f(t)| \leq M e^{at} \text{ as } t \rightarrow \infty$$

$$\mathcal{L}\left\{ \frac{e^{3t} - 1}{t} \right\} = \int_s^\infty \mathcal{L}\{e^{3t} - 1\} d\sigma \quad \text{---}$$

$$\mathcal{L}\{e^{3t} - 1\} = \frac{1}{s-3} - \frac{1}{s}$$

$$\Rightarrow \int_s^\infty \left(\frac{1}{\sigma-3} - \frac{1}{\sigma} \right) d\sigma = \left(\ln|\sigma-3| - \ln|\sigma| \right) \Big|_s^\infty =$$

$$= \ln \left| \frac{\sigma-3}{\sigma} \right| \Big|_s^\infty = \cancel{\ln 1} - \ln \left(\frac{s-3}{s} \right) = \boxed{\ln \frac{s}{s-3}} \quad s > 3$$

$$\lim_{\sigma \rightarrow \infty} \frac{\sigma-3}{\sigma} = \frac{1}{1} = 1 \Rightarrow \ln 1 = 0$$

Find inverse Laplace transform.

#13
S7.4

$$F(s) = \frac{s}{(s-3)(s^2+1)} = \frac{A}{s-3} + \frac{Bs+C}{s^2+1} =$$

$$= \frac{A(s^2+1) + (Bs+C)(s-3)}{(s-3)(s^2+1)}$$

$$\Rightarrow s = A(s^2+1) + (Bs+C)(s-3)$$

$$s^2: 0 = A+B \quad \Rightarrow B = -A$$

$$s^1: 1 = -3B+C$$

$$s^0: 0 = A-3C \quad C = \frac{A}{3}$$

$$1 = -3(A) + \frac{A}{3}$$

$$1 = \left(3 + \frac{1}{3}\right)A \Rightarrow 1 = \frac{10}{3}A \Rightarrow A = \frac{3}{10} = 0.3$$

$$B = -A = -0.3, \quad C = \frac{A}{3} = 0.1$$

$$\therefore F(s) = \frac{0.3}{s-3} + \frac{-0.3s+0.1}{s^2+1} =$$

$$= 0.3 \frac{1}{s-3} - 0.3 \frac{s}{s^2+1} + 0.1 \frac{1}{s^2+1}$$

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = 0.3e^{3t} - 0.3 \cos t + 0.1 \sin t$$

$$F(s) = \frac{s}{(s-3)(s^2+1)} = \frac{1}{s-3} \cdot \frac{s}{s^2+1} = \mathcal{L}\{e^{3t}\} \cdot \mathcal{L}\{\cos t\}$$

$$f(t) = \mathcal{L}^{-1}\{F(s)\} = e^{3t} * \cos t =$$

$$= \int_0^t e^{3\tau} \cos(t-\tau) d\tau = \int_0^t \underbrace{e^{3(t-\tau)}}_{e^{3t} e^{-3\tau}} \cos \tau d\tau =$$

$$= e^{3t} \underbrace{\int_0^t e^{-3\tau} \cos \tau d\tau}_I : \text{twice by parts to get equation for } I$$

Thus: $f * g = g * f$