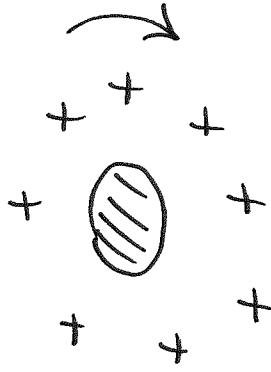


Note When circulation is taken over infinitesimal loop, it gives vorticity per unit area.



Orientation of the trace + will not change since flow is irrotational.

The character of streamlines depends on the value of circulation Γ .

We found

$$u_r = \frac{1}{r} \frac{\partial \psi}{\partial \theta} = U \left(1 - \frac{a^2}{r^2}\right) \cos \theta$$

$$u_\theta = -\frac{\partial \psi}{\partial r} = -U \left(1 + \frac{a^2}{r^2}\right) \sin \theta + \frac{\Gamma}{2\pi r}$$

where $\Gamma = -2\pi \bar{C}_1$: circulation around the cylinder, $\Gamma < 0$.

Def Stagnation points are points where velocity is zero.

$$\vec{u} = u_r \hat{r} + u_\theta \hat{\theta}$$

$$\vec{u} = 0 \Rightarrow u_r = 0, \quad u_\theta = 0$$

$$u_r = 0 \Rightarrow U \left(1 - \frac{a^2}{r^2} \right) \cos \theta = 0 \Rightarrow r = a \quad \text{or} \quad \cos \theta = 0$$

$$0 \leq \theta < 2\pi \Rightarrow \cos \theta = 0 \quad \text{when} \quad \theta = \frac{\pi}{2} \quad \text{or} \quad \theta = \frac{3\pi}{2}$$

$$u_\theta = 0 \Rightarrow -U \left(1 + \frac{a^2}{r^2} \right) \sin \theta + \frac{\Gamma}{2\pi r} = 0$$

$$\text{Let } B = -\frac{\Gamma}{2\pi U a} = \frac{\Gamma}{2U} \left(-\frac{1}{U a} \right) \Rightarrow \frac{\Gamma}{2\pi r} = -\frac{B U a}{r}$$

$$\Rightarrow u_\theta = 0 \Rightarrow -U \left(1 + \frac{a^2}{r^2} \right) \sin \theta - \frac{B U a}{r} = 0$$

$$-U \left[\left(1 + \frac{a^2}{r^2} \right) \sin \theta + \frac{B a}{r} \right] = 0 \quad \Rightarrow \quad \underbrace{\frac{B a}{r}}_{\neq 0} = 0 \Rightarrow \sin \theta < 0, \text{ i.e. } \theta \text{ is in the lower half plane}$$

Conditions for stagnation points are:

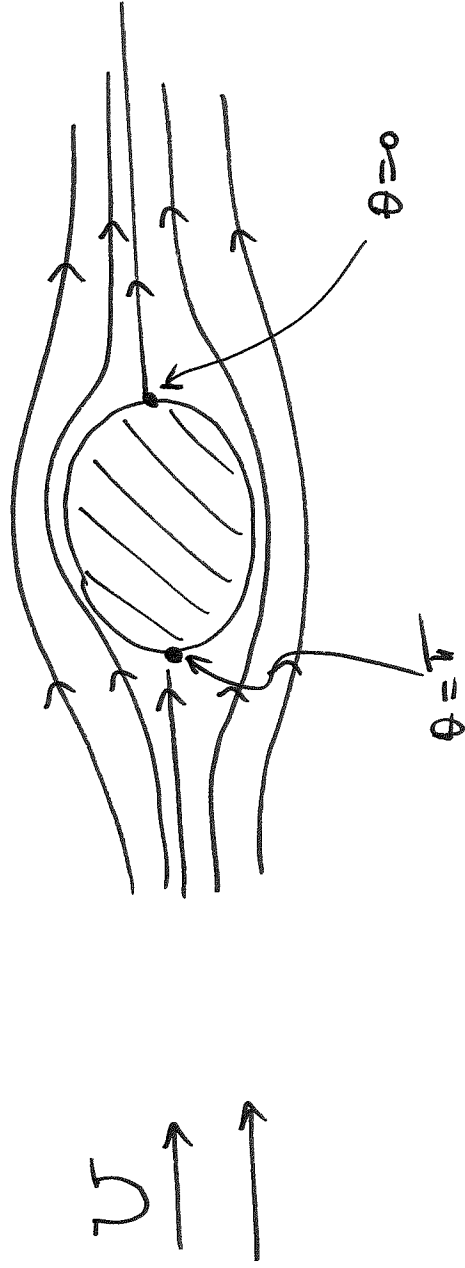
$$r=a \quad \text{or} \quad \theta = \frac{3\pi}{2}$$

Case 1: $r=a \Rightarrow$ stagnation points are on the cylinder

$$u_r|_{r=a} = 0 \quad \Rightarrow \quad \frac{\partial \phi}{\partial r} \Big|_{r=a} = -U [2a \sin \theta + B] = 0$$

$$\frac{\partial \phi}{\partial r} \Big|_{r=a} = 0 \quad \text{or} \quad 2a \sin \theta + B = 0 \quad \Rightarrow \quad \sin \theta = -\frac{B}{2}$$

$$\text{Case (a): } \boxed{B=0} \Rightarrow r=0 \Rightarrow \sin \theta = 0 \Rightarrow \theta = 0 \quad \text{or} \quad \theta = \pi$$

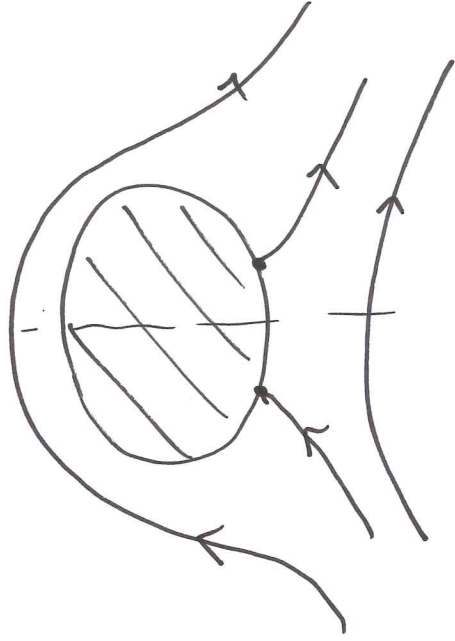
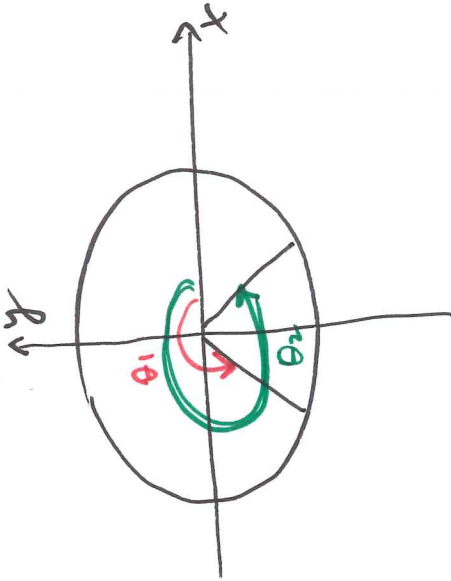


Case (b): $0 < B < 2$

$$B = -2 \sin \theta \Rightarrow$$

$$0 < -2 \sin \theta < 2 \quad \text{or} \quad -1 < \sin \theta < 0$$

two stagnation points at $r = a$ and $\theta = \theta_1, \theta = \theta_2$

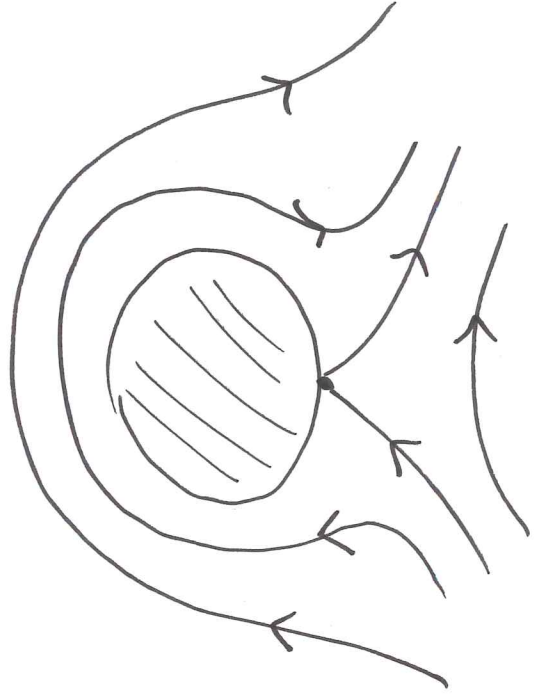


Case (c): $B = 2 \Rightarrow \sin \theta = -1$

$$\Rightarrow \theta = \frac{3\pi}{2}$$

$$\theta = \frac{3\pi}{2}$$

One stagnation pt at $r = a,$



Case (d): $B > 2$: no real solutions

Case 2: $\theta = \frac{3\pi}{2} \Rightarrow \cos \theta = 0 \Rightarrow u_r = 0$

$$u_\theta = -U \left[-\left(1 + \frac{a^2}{r^2}\right) + \frac{Ba}{r} \right] = 0 \Rightarrow [\dots] = 0$$

$$\Rightarrow r^2 - Bar + a^2 = 0$$

Two roots:

$$r = \frac{Ba \pm \sqrt{(Ba)^2 - 4a^2}}{2}$$

or

$$\frac{r}{a} = \frac{B}{2} \pm \sqrt{\left(\frac{B}{2}\right)^2 - 1}$$

point is inside cylinder \hookrightarrow

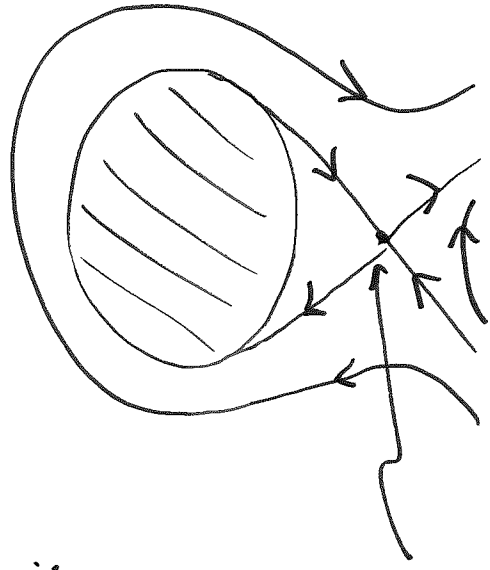
$$B > 2 \Rightarrow \frac{r}{a} < 1 \Rightarrow r < a$$

But the second root is outside the cylinder:

$$\frac{r}{a} = \frac{B}{2} + \sqrt{\left(\frac{B}{2}\right)^2 - 1}$$

(**)

We have one stagnation pt with $\theta = \frac{3\pi}{2}$ and r given by (**)



$$\left(r, \frac{3\pi}{2}\right)$$

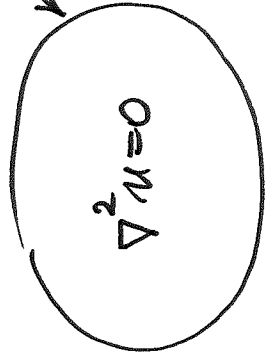
Properties of Laplace's equation

Recall the problem about steady state heat flow inside the circular domain.

$u(a, \theta) = f(\theta)$: prescribed temperature

We obtained solution valid for $r \leq a$:

$$u(r, \theta) = A_0 + \sum_{n=1}^{\infty} [A_n r^n \cos n\theta + B_n r^n \sin n\theta]$$



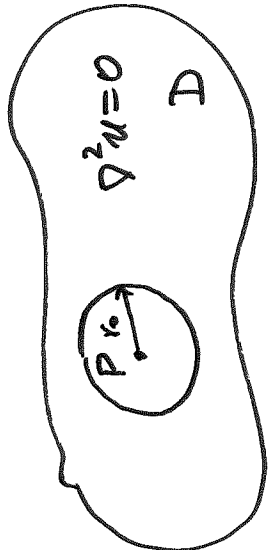
$$\nabla^2 u = 0$$

$$u(0, \theta) = A_0 = \frac{1}{2\pi} \int_{-\pi}^{\pi} f(\theta) d\theta$$

\therefore Temperature at $r=0$ equals the average value of temperature at the edge of the circle.

Def Functions that satisfy Laplace's equation are called harmonic functions.

More generally, consider a domain D and assume that $\nabla^2 u = 0$ in D .



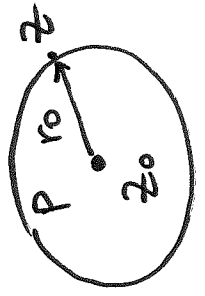
Take an arbitrary pt $P \in D$ and a circle w/ center at P and radius r_0 such that this circle is within domain D . Then

$$u(P) = \text{average value of } u(r_0, \theta) = \frac{1}{2\pi} \int_{-\pi}^{\pi} u(r_0, \theta) d\theta$$

$$z = z_0 + r_0 e^{i\theta}$$

$$u(z) = u(r_0, \theta)$$

$-\pi \leq \theta < \pi$
 points on the circle centered at P and radius r_0



This is a characteristic property of harmonic functions.

Maximum principle

The solution of $\nabla^2 u = 0$ in domain D attains its maximum on the boundary of D (unless $u \equiv \text{const}$).

Proof

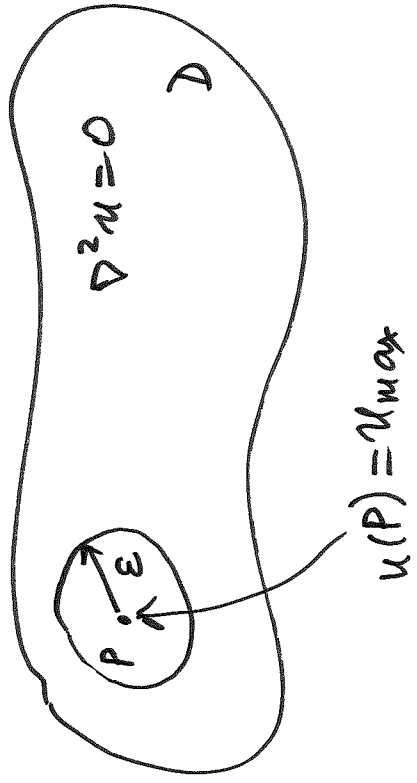
Ignore the case $u \equiv \text{const}$.

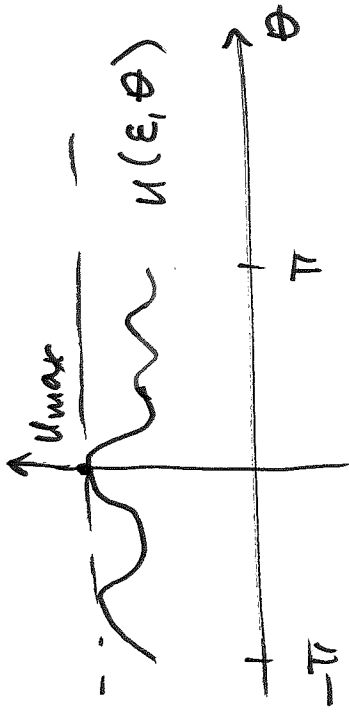
Assume that u achieves its max value at some pt P inside D . Enclose this point with a circle of radius ϵ so that circle is inside D .

By characteristic property of harmonic functions

$$u(P) = u_{\max} = \frac{1}{2\pi} \int_{-\pi}^{\pi} u(\epsilon, \theta) d\theta$$

average value of u on the circle centered at P w/ rad = ϵ





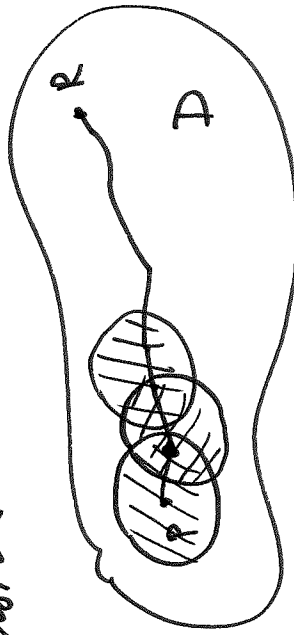
all values on the circle
 $u(\epsilon, \theta) \leq u_{max}$

The strict equality is achieved when

for all θ

$$u(\epsilon, \theta) = u_{max}$$

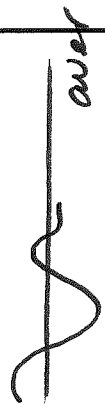
This is true for any $\epsilon \Rightarrow u = u_{max} = \text{const}$
 inside the disk centered at pt P.



Take any other point

that is inside the circle with center at P. The value at that other point is also u_{max} , and that other point is also u_{max} , and that other point is also u_{max} , and that other point is also u_{max} .

we can repeat the previous reasoning. In this way, we connect any point R in D with pt P by a broken line. The value inside of these disks is u_{max} . Since OHP can do this for any point inside D , this shows that $u = u_{max} = \text{const}$ everywhere in D . \downarrow



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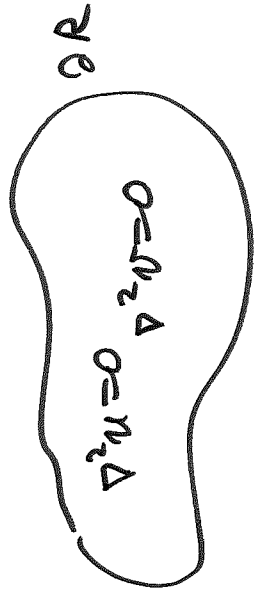
Note To prove that a harmonic function achieves its min on the boundary, use $-u(r, \theta)$ instead.

Well-posedness

Def We say that a problem is well-posed if there exists a unique solution that continuously depends on the nonhomogeneous data [small changes in data produce small changes in a solution].

Problem is well-posed if

- 1) solution exists
 - 2) solution is unique
 - 3) solution continuously depends on data
- a problem that is not well-posed is called ill-posed.

BVP with Dirichlet BCConsider a region R 

$$\nabla^2 u = 0 \quad \text{in } R \quad u|_{\partial R} = f$$

$$\nabla^2 v = 0 \quad \text{in } R \quad v|_{\partial R} = g$$

Let $f \approx g$.