

## Number Systems

**Base  $\beta$**

$$x = \pm(.a_1 a_2 a_3 \dots a_i \dots)_{\beta} \beta^e, \quad 1 \leq a_i < \beta$$

**Chopping**

$$\tilde{x} = \pm(.a_1 a_2 a_3 \dots a_i)_{\beta} \beta^e$$

**Rounding**

$$\tilde{x} = \begin{cases} \pm(.a_1 \dots a_i)_{\beta} \beta^e, & a_{i+1} < \frac{\beta}{2} \\ \pm[(a_1 \dots a_i)_{\beta} \beta^e + (.0 \dots 1)_{\beta} \beta^e], & a_{i+1} \geq \frac{\beta}{2} \end{cases}$$

**Error**

**Error:**  $e(\tilde{x}) = |x - \tilde{x}|$

**Relative Error:**  $re(\tilde{x}) = \left| \frac{x - \tilde{x}}{x} \right|$

## Linear Systems, $Ax = b$

THM: Given a matrix  $A$ , the following are equivalent

1. The Equation  $Ax = b$  has a unique solution
2.  $A$  is invertible.
3.  $\det(A) \neq 0$
4.  $Ax = 0$  has a unique solution,  $x = 0$
5. The columns of  $A$  are linearly independent
6. The eigenvalues,  $\lambda$ , of  $A$  are non-zero.

**Gaussian Elimination:**  $A = LU$

**Gaussian Elimination with pivoting:**  $PA = LU$

**Norms**

**Properties of Vector Norms:**

$$\|x\| \geq 0, \quad \|x\| = 0 \Rightarrow x = 0$$

$$\|\lambda x\| = |\lambda| \|x\|, \quad \lambda \text{ scalar}$$

$$\|x + y\| \leq \|x\| + \|y\|$$

**Vector Norms:**

$$l_{\infty} : \quad \|x\|_{\infty} = \max_{1 \leq i \leq n} |x_i|$$

$$l_1 : \quad \|x\|_1 = \sum_{i=1}^n |x_i|$$

$$l_2 : \quad \|x\|_2 = \left( \sum_{i=1}^n x_i^2 \right)^{\frac{1}{2}}$$

## Matrix Norm:

$$\|A\| = \max_{\|u\| \neq 0} \{ \|Au\| / \|u\| : u \in \mathbf{R}^n \}$$

**Properties of Matrix Norms:**

$$\|A\| \geq 0, \quad \|A\| = 0 \Leftrightarrow A = 0$$

$$\|\lambda A\| = |\lambda| \|A\|$$

$$\|A + B\| \leq \|A\| + \|B\|$$

$$\|Ax\| \leq \|A\| \|x\|$$

$$\|AB\| \leq \|A\| \|B\|$$

## Examples of Matrix Norms:

$$l_{\infty} \text{ Matrix Norm: } \|A\|_{\infty} = \max_{1 \leq i \leq n} \sum_{j=1}^n |a_{i,j}|$$

$$l_1 \text{ Matrix Norm: } \|A\|_1 = \max_{1 \leq j \leq n} \sum_{i=1}^n |a_{i,j}|$$

$$l_2 \text{ Matrix Norm: } \|A\|_2 = \sqrt{\rho(A^*A)}$$

## Stability

**Condition Number:**  $\kappa(A) = \|A^{-1}\| \|A\|$

**Residual:**  $r = b - Ax$

**THM:**

$$\frac{1}{\kappa(A)} \frac{\|r\|}{\|b\|} \leq \frac{\|e\|}{\|x\|} \leq \kappa(A) \frac{\|r\|}{\|b\|}$$

## Iterative Methods

$A = (L + D + U)$  where  $D$  is a diagonal matrix,  $L$  is lower triangular and  $U$  is upper triangular.

**Jacobi:**  $Dx^{n+1} = -(L + U)x^n + b$

**Gauss-Seidel:**  $Dx^{n+1} = -(Lx^{n+1} + Ux^n) + b$

**SOR:**  $(D + \omega L)x^{n+1} = ((1 - \omega)D - \omega U)x^n + \omega b$

## Root Finding Methods

**Newton's Methods:**  $x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)}$

**Secant Methods:**  $x_{n+1} = x_n - f(x_n) \frac{x_n - x_{n-1}}{f(x_n) - f(x_{n-1})}$

**Error Bound for Bisection Method:**

$$|\alpha - x_n| \leq \left( \frac{1}{2} \right)^n |b_0 - a_0|$$

### Polynomial Interpolation

Let  $f$  be defined on  $[a, b]$ ;  $x_0, x_1, \dots, x_n$ :  $n + 1$  distinct points in  $[a, b]$ . Let  $p_n$  be the interpolating polynomial of degree  $\leq n$ . Then

$$f(x) = p_n(x) + \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0) \dots (x - x_n)$$

for some  $\xi \in [a, b]$ .

### Chebyshev Points

$$x_k = \cos((2k+1)\pi/2)n, \quad k = 0, 1, \dots, n-1$$

or

$$x_k = -\cos \pi kn, \quad k = 0, 1, \dots, n$$

### Hermite Interpolation

Given  $f, x_0, x_1, \dots, x_n$ :  $n + 1$  distinct points, the Hermite interpolating polynomial  $p(x)$  ( $\deg p \leq 2n + 1$ ) is

$$p(x) = \sum_{i=0}^n \left( f(x_i)h_i(x) + f'(x_i)\tilde{h}_i(x) \right)$$

where

$$h_i(x) = (1 - 2(x - x_i)l_i^1)l_i^2(x), \quad \tilde{h}_i(x) = (x - x_i)l_i^2(x)$$

If  $f \in C^{(2n+2)}[a, b]$ ,  $p(x)$  is the Hermite interpolating polynomial, then

$$f(x) = p(x) + \frac{f^{(2n+2)}(\xi)}{(2n+2)!} (x - x_0)^2 \dots (x - x_n)^2$$

### Splines

Let  $a = x_0 < x_1 < \dots < x_{n-1} < x_n = b$ . A spline of degree  $m$  is a function  $S(x)$  which satisfies the following conditions:

- 1) For  $x \in [x_i, x_{i+1}]$ ,  $S(x) = S_i(x)$ : polynomial of degree  $\leq m$
- 2)  $S^{(m-1)}(x)$  exists and is continuous at the interior points  $x_1, \dots, x_{n-1}$ , i.e.  $\lim_{x \rightarrow x_i^-} S_{i-1}^{(m-1)}(x) = \lim_{x \rightarrow x_i^+} S_i^{(m-1)}(x)$

Let  $f$  be defined on  $[a, b]$ ,  $a = x_0 < x_1 < \dots < x_{n-1} < x_n = b$  and let  $S$  be the natural cubic spline interpolant of  $f$ . Then

$$1) |f(x) - S(x)| \leq \frac{5}{384} \max_{a \leq x \leq b} |f^{(4)}(x)|h^4$$

where  $h = \max_i |x_{i+1} - x_i|$

$$\int_a^b (S''(x))^2 dx \leq \int_a^b (f''(x))^2 dx$$

### Numerical Integration

$$\int_a^b f(x)dx \sim \sum_{i=0}^n c_i f(x_i)$$

### Trapezoid Rule:

$$T(h) = h \left( \frac{1}{2}f(x_0) + f(x_1) + \dots + f(x_{n-1}) + \frac{1}{2}f(x_n) \right)$$

### Local Error Estimate:

$$\int_a^{a+h} f(x)dx = h \frac{f(a) + f(a+h)}{2} - \frac{h^3}{12} f''(\xi)$$

### Global Error Estimate:

$$\int_a^b f(x)dx = T(h) - \frac{f''(\xi)}{12} h^2(b-a)$$

### Simpson's Rule:

$$S(h) = h \left( \frac{1}{3}f(x_0) + \frac{4}{3}f(x_1) + \frac{2}{3}f(x_2) + \dots + \frac{2}{3}f(x_{n-2}) + \frac{4}{3}f(x_{n-1}) + \frac{1}{3}f(x_n) \right)$$

### Error:

$$\int_a^b f(x)dx = S(h) - \frac{f^{(4)}(\xi)}{180} h^4(b-a)$$

### Orthogonal Polynomials:

The inner product of two functions  $f$  and  $g$  on  $[a, b]$  with the weighting function  $w(x)$  is

$$\langle f, g \rangle = \int_a^b f(x)g(x)w(x)dx$$

### Properties:

- 1)  $\langle f, f \rangle \geq 0, \langle f, f \rangle = \|f\|^2 = 0 \Leftrightarrow f = 0$
- 2)  $\langle f, \alpha g + h \rangle = \alpha \langle f, g \rangle + \langle f, h \rangle$

### Gaussian Quadrature:

$$\int_{-1}^1 f(x)dx \sim \sum_{i=1}^n c_i f(x_i)$$

where  $x_i, i = 1, \dots, n$  are roots of Legendre polynomial  $P_n(x)$ .

### IVP for ODEs:

$$y' = f(t, y), \quad y(a) = \alpha, \quad a \leq t \leq b$$

### Euler's Method:

$$u_{n+1} = u_n + hf(t_n, u_n), \quad u_0 = \alpha$$

**Local Truncation Error:**  $\tau_n = \frac{h^2}{2} y''(\tilde{t}_n)$   
**Global Error:**

$$|y_n - u_n| \leq \frac{hM}{2L} \left( e^{L(t_n-a)} - 1 \right)$$

where  $L$  is a Lipschitz constant,  $M = \max |y''(t)|$ .

#### Modified Euler's Method:

$$k_1 = f(t_n, u_n), \quad k_2 = f(t_n + h, u_n + hk_1)$$

$$u_{n+1} = u_n + \frac{h}{2}(k_1 + k_2)$$

#### 4th Order Runge-Kutta Method:

$$k_1 = f(t_n, u_n), \quad k_2 = f(t_n + \frac{h}{2}, u_n + \frac{h}{2}k_1)$$

$$k_3 = f(t_n + \frac{h}{2}, u_n + \frac{h}{2}k_2), \quad k_4 = f(t_n + h, u_n + hk_3)$$

$$u_{n+1} = u_n + \frac{h}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

#### Backward Euler's Method:

$$u_{n+1} = u_n + hf(u_{n+1})$$

#### System of ODEs:

$$y' = Ay, \quad A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

#### Exact Solution:

$$y(t) = \alpha_1(0) e^{\lambda_1 t} p_1 + \alpha_2(0) e^{\lambda_2 t} p_2$$

#### Forward Euler:

$$u_n = \alpha_1(0) (1 + h\lambda_1)^n p_1 + \alpha_2(0) (1 + h\lambda_2)^n p_2$$

#### Backward Euler:

$$u_n = \alpha_1(0) \left( \frac{1}{1 - h\lambda_1} \right)^n p_1 + \alpha_2(0) \left( \frac{1}{1 - h\lambda_2} \right)^n p_2$$

#### Multistep Methods:

##### General 2-Step Method:

$$\alpha_0 u_{n+1} + \alpha_1 u_n + \alpha_2 u_{n-1} = h [\beta_0 f(u_{n+1}) + \beta_1 f(u_n) + \beta_2 f(u_{n-1})]$$

##### Adams-Basforth:

$$u_{n+1} = u_n + \frac{h}{2} [3f(u_n) - f(u_{n-1})]$$

##### Adams-Moulton

$$u_{n+1} = u_n + \frac{h}{12} [5f(u_{n+1}) + 8f(u_n) - f(u_{n-1})]$$

##### Leap-Frog

$$u_{n+1} = u_{n-1} + 2hf(u_n)$$

#### BDF: Backward Differentiation Formula — Gear's Method

$$\frac{3}{2}u_{n+1} - 2u_n + \frac{1}{2}u_{n-1} = hf(u_n)$$

#### Computing eigenvalues and eigenvectors

$$Ax = \lambda x, \quad x \neq 0$$

$\lambda$  : eigenvalue

$x$  : associated eigenvector

#### Power method:

Idea:  $v, Av, A^2v, \dots$

1.  $v^{(0)}$ : given,  $\|v^{(0)}\|_2 = 1$
2. for  $k = 1, 2, \dots$
3.  $w = Av^{(k-1)}$
4.  $v^{(k)} = w/\|w\|_2$
5.  $\lambda^{(k)} = (v^{(k)})^T Av^{(k)}$

#### Inverse iteration:

Idea: apply power method to  $A^{-1}$ ,  $(A - \mu I)^{-1}$ ,  $\mu$ : shift

1.  $v^{(0)}$ : given,  $\|v^{(0)}\|_2 = 1$
2. for  $k = 1, 2, \dots$
3. solve  $(A - \mu I)w = v^{(k-1)}$
4.  $v^{(k)} = w/\|w\|_2$
5.  $\lambda^{(k)} = (v^{(k)})^T Av^{(k)}$

#### Rayleigh quotient iteration:

Idea: update  $\mu$

1.  $v^{(0)}$ : given,  $\|v^{(0)}\|_2 = 1$ ,  $\lambda^{(0)} = (v^{(0)})^T Av^{(0)}$
2. for  $k = 1, 2, \dots$
3. solve  $(A - \lambda^{(k-1)}I)w = v^{(k-1)}$
4.  $v^{(k)} = w/\|w\|_2$
5.  $\lambda^{(k)} = (v^{(k)})^T Av^{(k)}$

#### Least Squares:

$A\vec{z} = \vec{b}$ :  $m \times n$  system with  $m \geq n$

$A^T A\vec{z} = A^T \vec{b}$ : normal equations