

HW problem #2: \nearrow see lecture #29

Idea is similar to derivation of local truncation error in trapezoid rule, but one needs to use 3 points $x_0 = a$, $x_1 = a + h + \epsilon$ and $x_2 = b$, $h = \frac{b-a}{2}$, and interpolate $f(x)$ with 2nd degree interpolating polynomial

$$f(x) = p_2(x) + \frac{f'''(\xi(x))}{3!} (x-x_0)(x-x_1)(x-x_2)$$

exact approx. error

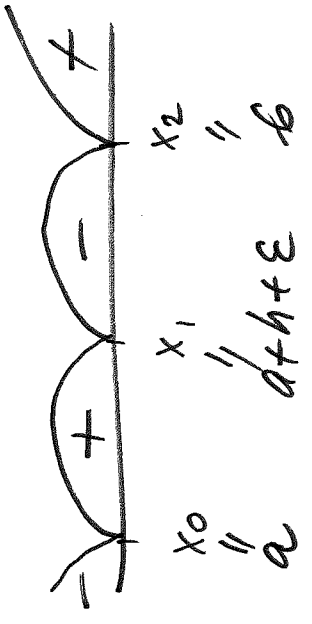
$$\int_a^b f(x) dx = \int_a^b p_2(x) dx + \int_a^b \frac{f'''(\xi(x))}{3!} (x-x_0)(x-x_1)(x-x_2) dx$$

exact quadrature error in quadrature

Recall, generalized MVT:

$$\int_a^b f(x)g(x) dx = f\left(\frac{a+b}{2}\right) \int_a^b g(x) dx, \quad g(x) \geq 0$$

If we use $p_1(x)$, the 1st degree interpolating polynomial, as in the derivation of Trapezoid rule, $(x-x_0)(x-x_1)$ does not change sign on $[a, a+h]$.



In our case, $(x-x_0)(x-x_1)(x-x_2) = w_2(x)$ changes its sign inside $[a, b]$.

Hence we cannot use generalized MIT directly.

Remedy: apply integration by parts to

$$\int_a^b \frac{f'''(\xi(x))}{3!} \underbrace{(x-x_0)(x-x_1)(x-x_2)}_u dx$$

$u = (x-x_0)(x-x_1)(x-x_2)$: cubic polynomial

$du = (\text{polynomial of degree 2 with roots that are not inside } [a, b]) dx$

$$d^3v = \frac{f'''(\xi(x))}{3!} dx$$

$$v = \frac{f''(\xi(x))}{3!} \Big|_a^b$$

Recall integration by parts formula:

$$\int_a^b u dv = uv \Big|_a^b - \int_a^b v du$$

$$\begin{aligned} \text{Ex} \quad \int_0^{\pi} x \sin x \, dx &= \left. \begin{array}{l} u = x \quad dv = \sin x \, dx \\ du = dx \quad v = -\cos x \end{array} \right|_0^{\pi} = -x \cos x \Big|_0^{\pi} + \int_0^{\pi} \cos x \, dx = \\ &= \pi + \sin x \Big|_0^{\pi} = \pi \end{aligned}$$

Then apply generalized MVT.

$$\int_a^b p_2(x) dx = \text{quadrature}$$

Use some symbolic software like Maple, Mathematica (there is free online version of Mathematica) or Matlab w/ symbolic variables (Matlab uses Maple commands). The installed version of Matlab has symbolic tool box.

Back to
Backward Euler's method

Absolute stability

$$y' = \lambda y$$

Backward Euler:
$$u_{n+1} = u_n + h \underbrace{f(u_{n+1})}_{\lambda u_{n+1}} = u_n + h \lambda \underbrace{u_{n+1}}$$

$$f(y) = \lambda y$$

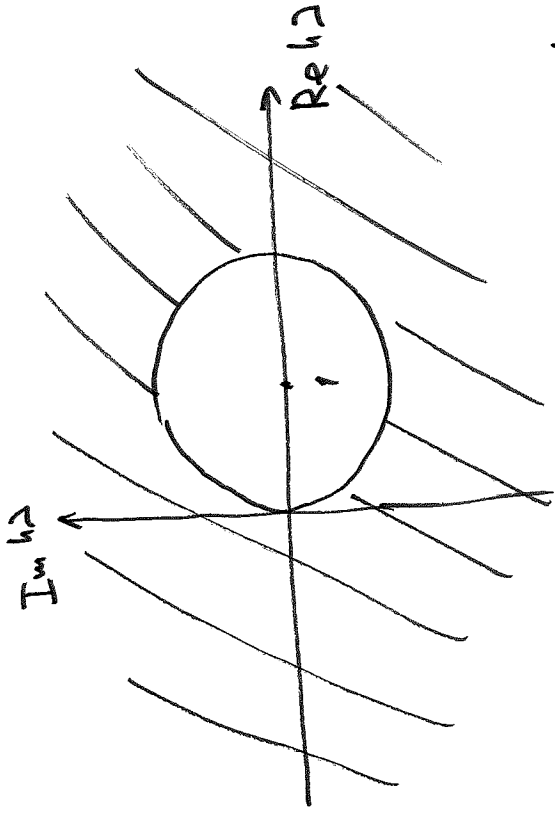
$$\Rightarrow (1 - h\lambda) u_{n+1} = u_n \Rightarrow u_{n+1} = \frac{1}{1 - h\lambda} u_n$$

amplification factor
for Backward Euler

$$\Rightarrow u_n = \left(\frac{1}{1 - h\lambda} \right)^n u_0$$

$$u_n \text{ is bounded for all } n \Rightarrow \left| \frac{1}{1 - h\lambda} \right| \leq 1 \quad \text{or} \quad |h\lambda - 1| \geq 1$$

Since $\text{Re} \lambda < 0$, we have no restriction on h



Method is called A-stable if the region of absolute stability includes the entire half-plane.

Def A system of ODEs, $y' = Ay$, is called a stiff system if A has negative e -values with greatly different magnitudes.

Ex $A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

Assume $\lambda_1 \ll \lambda_2 < 0$

$$y(t) = \alpha_1(0) e^{\lambda_1 t} p_1 + \alpha_2(0) e^{\lambda_2 t} p_2: \text{exact}$$

$$u_n = \alpha_1(0) (1 + h\lambda_1)^n p_1 + \alpha_2(0) (1 + h\lambda_2)^n p_2: \text{Euler's method}$$

$$u_n = \alpha_1(0) \left(\frac{1}{1 - h\lambda_1} \right)^n p_1 + \alpha_2(0) \left(\frac{1}{1 - h\lambda_2} \right)^n p_2: \text{backward Euler's method}$$

We require that both $h\lambda_1$ and $h\lambda_2$ be in the region of absolute stability. For Euler's method, we impose

$$h \leq -\frac{1}{\lambda_1}$$

small

$$h \leq -\frac{1}{\lambda_2}$$

$$\lambda_1 \ll \lambda_2 < 0$$

For backward Euler, there is no restriction on h .
 \rightarrow we can use larger h and we choose h to have some accuracy.

Note

Implicit schemes are implemented as predictor-corrector methods.

Ex $u_{n+1} = u_n + h f(u_{n+1})$

$\Rightarrow u_{n+1}^{(1)} = u_n + h f(u_n) : \underline{\text{predictor}}$

$u_{n+1}^{(k+1)} = u_n + h f(u_{n+1}^{(k)}) : \underline{\text{corrector}}$

```

> x0:=a;
(1)
> x1:=a+h+epsilon;
(2)
> x2:=a+2*h;
(3)
> simplify(int((x-x0)*(x-x1),x=x0..x2));
(4)
      3
     h  - 2*epsilon*h
      2
(5)  f0:=f(a);
(6)  f01:=f(a+h+epsilon)-f(a);
(7)  f02:=f(a+2*h)-f(a+h+epsilon);
(8)  f012:=simplify((f01-f02)/(x2-x0));
      1
     f(a+2*h)+f(a+h+epsilon)+f(a)-f(a)
      3
     h  - 2*epsilon*h
      2
(9)  p2:=f(a)+f(a+h+epsilon)-f(a);
      1
     f(a+2*h)-f(a)
      1
     h  - 2*epsilon*h
      2
(10) p2int:=int(1/2*(f(a+2*h)+f(a))-
              (f(a)+f(a+h+epsilon)-f(a))*
              (x-x1),x=x0..x2);

```


$$\left(\frac{1}{2} + \frac{f(a+2h)h + f(a+h)h + \epsilon}{f(a)h - f(a)\epsilon} \right) \frac{h^2(-h^2 + \epsilon^2)}{2}$$

> eval(f012x,x=x0) !
 Error, numeric exception: division by zero

```
> simplify(int((x-x0)*(x-x1)*(x-x2),x=x0..x2));
```

(18)

```
> simplify(int(collect(int((tau-x0)*(tau-x1)*(tau-x2),tau=x0..x),x),x),x=x0..x2));
```

$$\frac{15}{4} h^5 + \frac{3}{4} \epsilon h^4$$

(19)

```
> g:=collect(int((tau-x0)*(tau-x1)*(tau-x2),tau=x0..x),x);
```

(20)

$$-2h) \left(x^2 - a(-a-h-\epsilon) \right) \frac{1}{2} (-a(-a-h-\epsilon) + (-2a-h$$

$$- \epsilon) (-a-2h) a^2 \frac{1}{4} a^4 - \frac{3}{1} (-3a-3h-\epsilon) a^3 + a^2 (-a-h-\epsilon) (-a$$

-2h)

```
> collect(limit(f012x,x=x2),h);
```

(21)

$$- \frac{1}{4} \frac{h^2(-h^2 + \epsilon^2)(-h + \epsilon)}{1} (-2D(f)(a+2h)h^3 + (3f(a+2h) - 4f(a+h + \epsilon)$$

$$+ f(a)h^2 + (2D(f)(a+2h)\epsilon^2 + 2f(a+2h)\epsilon - 2f(a)\epsilon)h - f(a+2h)\epsilon^2$$

$$+ f(a)\epsilon^2)$$

```
> simplify(int((tau-x0)*(tau-x1)*(tau-x2),tau=x0..x2));
```

(22)

$$\frac{3}{4} \epsilon h^3$$

>