

## Statistical Theory for Generalized Linear Models

The generalized linear model extends beyond the normal distribution to the exponential family of distributions,

$$p(y; \theta, \phi) = \exp \left[ \frac{y\theta - b(\theta)}{a(\phi)} + c(y, \phi) \right],$$

where  $p(y; \theta, \phi)$  is the pmf or pdf of  $Y$ ,  $a(\cdot)$ ,  $b(\cdot)$ , and  $c(\cdot)$  are known functions,  $\theta = g_c(\mu)$  is the canonical parameter, and  $\phi$  is the dispersion parameter. Table 15.9 in the text lists the values of  $a(\cdot)$ ,  $b(\cdot)$ , and  $c(\cdot)$  for several well-known distributions. The log-likelihood function for a sample is then

$$\log L(\boldsymbol{\theta}, \phi; \mathbf{y}) = \sum_{i=1}^n \left[ \frac{Y_i \theta_i - b(\theta_i)}{a_i(\phi)} + c(Y_i, \phi) \right].$$

Using the results that

$$E \left( \frac{\partial \log L(\theta, \phi; y)}{\partial \theta} \right) = 0 \text{ and}$$
$$E \left( \frac{\partial^2 \log L(\theta, \phi; y)}{\partial \theta^2} \right) + E \left( \frac{\partial \log L(\theta, \phi; y)}{\partial \theta} \right)^2 = 0$$

we can show that

$$E(Y) = \mu = b'(\theta) \text{ and}$$
$$V(Y) = a(\phi)b''(\theta) = a(\phi)v(\mu).$$

### Maximum Likelihood Estimation

For a model with

$$g(\mu_i) = \eta_i = \beta_0 + \beta_1 X_{i1} + \beta_2 X_{i2} + \cdots + \beta_k X_{ik},$$

we find the MLE's by taking the derivative of each term in the sum for  $l = \log L(\boldsymbol{\theta}, \phi; \mathbf{y})$  with respect to a parameter  $\beta_j$  using the chain rule,

$$\frac{\partial l_i}{\partial \beta_j} = \frac{\partial l_i}{\partial \theta_i} \times \frac{d\theta_i}{d\mu_i} \times \frac{d\mu_i}{d\eta_i} \times \frac{\partial \eta_i}{\partial \beta_j} \text{ for each } j.$$

We have

$$\begin{aligned}\frac{\partial l_i}{\partial \theta_i} &= \frac{y_i - b'(\theta_i)}{a_i(\phi)} = \frac{y_i - \mu_i}{a_i(\phi)}, \\ \frac{d\theta_i}{d\mu_i} &= \frac{1}{\partial \mu_i / \partial \theta_i} = \frac{1}{\partial b'(\theta_i) / \partial \theta_i} = \frac{1}{b''(\theta_i)} = \frac{1}{v(\mu_i)}, \\ \frac{\partial \eta_i}{\partial \beta_j} &= x_{ij},\end{aligned}$$

leading to the estimating equations

$$\sum_{i=1}^n \frac{Y_i - \mu_i}{a_i v(\mu_i)} \times \frac{d\mu_i}{d\eta_i} \times x_{ij} = 0.$$

These equations can be simplified if  $g(\cdot)$  is the canonical link, but in most circumstances iterative methods are required to solve for the MLE's.

### **IWLS for solving for the MLE's**

Let

$$\begin{aligned}Z_i &\equiv \eta_i + (Y_i - \mu_i) \frac{d\eta_i}{d\mu_i} \\ &= \eta_i + (Y_i - \mu_i) g'(\mu_i).\end{aligned}$$

Then

$$\begin{aligned}E(Z_i) &= \eta_i = \beta_0 + \beta_1 X_{i1} + \beta_2 X_{i2} + \cdots + \beta_k X_{ik}, \text{ and} \\ V(Z_i) &= [g'(\mu_i)]^2 a_i v(\mu_i).\end{aligned}$$

These equations are the motivation for the iteratively (re)weighted least squares procedure for computing the maximum likelihood estimates:

Step 1: Start with initial estimates of  $\hat{\mu}_i$  and  $\hat{\eta}_i$ , call them  $\hat{\mu}_i^{(0)}$  and  $\hat{\eta}_i^{(0)}$ .

Step 2: For iteration  $l$ , compute the working response variable  $Z_i^{(l-1)}$  as follows,

$$Z_i^{(l-1)} = \eta_i^{(l-1)} + (Y_i - \mu_i^{(l-1)}) g'(\mu_i^{(l-1)})$$

with weights

$$W_i^{(l-1)} = \frac{1}{\left[g'(\mu_i^{(l-1)})\right]^2 a_i v(\mu_i^{(l-1)})}.$$

Step 3: Calculate the weighted least squares estimate of  $\mathbf{b}^{(l)}$ ,

$$\mathbf{b}^{(l)} = (\mathbf{X}'\mathbf{W}^{(l-1)}\mathbf{X})^{-1} \mathbf{X}'\mathbf{W}^{(l-1)}\mathbf{z}^{(l-1)}.$$

Step 4: Repeat steps 2 and 3 until convergence.

For canonical links, IWLS implements a Newton-Raphson algorithm, but more generally is equivalent to Fisher's method of scoring.

The dispersion parameter  $\phi$  is typically estimated via

$$\tilde{\phi} = \frac{1}{n - k - 1} \sum_{i=1}^n \frac{(Y_i - \hat{\mu}_i)^2}{a_i v(\hat{\mu}_i)},$$

and the estimated asymptotic covariance matrix of  $\mathbf{b}$  is,

$$\hat{V}(\mathbf{b}) = \tilde{\phi} (\mathbf{X}'\mathbf{W}\mathbf{X})^{-1}.$$

We can use the estimation approach developed above by just specifying first and second moment relationships for  $Y$  without specifying a conditional distribution. Viewed this way, the estimates are called quasi-likelihood estimates.