

The Matrix-Based Approach to the General Linear Model - a little bit more

Random Regressors

All of the theory that we have been learning about for the general linear model so far has assumed that the matrix \mathbf{X} is fixed, not random. In some applications this assumption is not true, so we will consider some situations when \mathbf{X} is random. For our model $\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \boldsymbol{\varepsilon}$, when \mathbf{X} was fixed we assumed that $E(\boldsymbol{\varepsilon}) = \mathbf{0}$ and $V(\boldsymbol{\varepsilon}) = \sigma_\varepsilon^2 \mathbf{I}_n$. When \mathbf{X} is random we will make three assumptions:

i) the distribution of $\boldsymbol{\varepsilon}$ is not affected by \mathbf{X} , so that \mathbf{X} and $\boldsymbol{\varepsilon}$ are independent and thus the conditional distribution is $\boldsymbol{\varepsilon}|\mathbf{X}_0 \sim N_n(\mathbf{0}, \sigma_\varepsilon^2 \mathbf{I}_n)$ for any possible sample \mathbf{X}_0 .

ii) the distribution of \mathbf{X} does not depend on $\boldsymbol{\beta}$ or σ_ε^2 .

iii) the covariance matrix of \mathbf{X} is nonsingular.

When these assumptions hold, our results from this chapter are still valid. Here is an example of the reasoning: for a particular sample \mathbf{X}_0 , the expected value of \mathbf{b} is:

$$E(\mathbf{b}|\mathbf{X}_0) = E[(\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y}|\mathbf{X}_0] = (\mathbf{X}'_0\mathbf{X}_0)^{-1}\mathbf{X}'_0E(\mathbf{y}|\mathbf{X}_0) = (\mathbf{X}'_0\mathbf{X}_0)^{-1}\mathbf{X}'_0\mathbf{X}_0\boldsymbol{\beta} = \boldsymbol{\beta}.$$

Since this conditional distribution of $\mathbf{b}|\mathbf{X}_0$ is the same for any value of \mathbf{X}_0 , it is therefore the unconditional distribution of \mathbf{b} , so \mathbf{b} is unconditionally unbiased. In a similar way, when conducting likelihood-based inference there is now a density for \mathbf{X} , $p(\mathbf{X}) = \prod_{i=1}^n p(\mathbf{x}'_i)$, but as long as our assumptions above hold, it factors away from the part of the joint density $p(\mathbf{y}, \mathbf{X})$ involving \mathbf{y} , so our results (MLE, likelihood-ratio test, etc.) are unchanged.

Specification Error (consequences of underfitting)

One question at the end of this chapter is the effect on estimates of $\boldsymbol{\beta}$ when the model is underspecified, meaning that not all important covariates are included. Suppose the true model is

$$\mathbf{y}^* = \mathbf{X}^* \boldsymbol{\beta} + \boldsymbol{\varepsilon} = \mathbf{X}_1^* \boldsymbol{\beta}_1 + \mathbf{X}_2^* \boldsymbol{\beta}_2 + \boldsymbol{\varepsilon},$$

where \mathbf{X}^* and $\boldsymbol{\beta}$ have been partitioned into a first part \mathbf{X}_1^* based on variables in the model, and a second part \mathbf{X}_2^* consisting of variables that should have been included but were not, and the corresponding partitions of $\boldsymbol{\beta}$, $\boldsymbol{\beta}_1$ and $\boldsymbol{\beta}_2$. As we have used previously, the use of a * with \mathbf{X} and \mathbf{y} indicates that they are expressed as deviations from their expectations ($\mathbf{y}^* = \mathbf{y} - E(\mathbf{y})$), so that the intercept term β_0 is eliminated, as illustrated in section 6.3. If we then fit a model just using the matrix \mathbf{X}_1^* , the model can be written as:

$$\mathbf{y}^* = \mathbf{X}_1^* \boldsymbol{\beta}_1 + \tilde{\boldsymbol{\varepsilon}},$$

where $\tilde{\boldsymbol{\varepsilon}} = \mathbf{X}_2^* \boldsymbol{\beta}_2 + \boldsymbol{\varepsilon}$, so that the error term incorporates the missing part of the model. The least-squares estimator for this (incorrect) model can be written as:

$$\begin{aligned}
\mathbf{b}_1 &= (\mathbf{X}_1^* \mathbf{X}_1^*)^{-1} \mathbf{X}_1^* \mathbf{y}^* \\
&= \left(\frac{1}{n} \mathbf{X}_1^* \mathbf{X}_1^* \right)^{-1} \frac{1}{n} \mathbf{X}_1^* \mathbf{y}^* \\
&= \left(\frac{1}{n} \mathbf{X}_1^* \mathbf{X}_1^* \right)^{-1} \frac{1}{n} \mathbf{X}_1^* (\mathbf{X}_1^* \boldsymbol{\beta}_1 + \mathbf{X}_2^* \boldsymbol{\beta}_2 + \boldsymbol{\varepsilon}) \\
&= \boldsymbol{\beta}_1 + \left(\frac{1}{n} \mathbf{X}_1^* \mathbf{X}_1^* \right)^{-1} \frac{1}{n} \mathbf{X}_1^* \mathbf{X}_2^* \boldsymbol{\beta}_2 + \left(\frac{1}{n} \mathbf{X}_1^* \mathbf{X}_1^* \right)^{-1} \frac{1}{n} \mathbf{X}_1^* \boldsymbol{\varepsilon}.
\end{aligned}$$

By taking probability limits, it can be shown that

$$\text{plim } \mathbf{b}_1 = \boldsymbol{\beta}_1 + \boldsymbol{\Sigma}_{11}^{-1} \boldsymbol{\Sigma}_{12} \boldsymbol{\beta}_2,$$

showing that \mathbf{b}_1 is inconsistent unless the two sets of covariates are uncorrelated ($\boldsymbol{\Sigma}_{12} = 0$) or the excluded covariates have slopes of $\boldsymbol{\beta}_2 = \mathbf{0}$. It is also shown that the asymptotic covariance between \mathbf{X}_1^* and $\tilde{\boldsymbol{\varepsilon}}$ is not generally 0.

Confidence Intervals and Prediction Intervals for a particular covariate vector

This topic is presented as a problem in our text (Exercise 9.14), and is important to understand. Often, once we have a fitted model $\hat{\mathbf{y}} = \mathbf{X}\hat{\boldsymbol{\beta}}$ we wish to predict either $E(y)$ or y for a particular covariate vector value $\mathbf{x}'_0 = [1, x_{01}, \dots, x_{0k}]$. The way to predict $E(y)$ or y is straightforward, we use $\widehat{E(y_0)} = \hat{y}_0 = \mathbf{x}'_0 \hat{\mathbf{b}}$. However, we also typically want an interval estimate of this value. If we are predicting $E(y)$, we call an interval estimate a confidence interval, our error in estimation is $\delta = \hat{y}_0 - E(y_0)$, and we can see that:

$$\begin{aligned}
E(\delta) &= E(\hat{y}_0 - E(y_0)) = E(\hat{y}_0) - \mathbf{x}'_0 \boldsymbol{\beta} = \mathbf{x}'_0 E(\mathbf{b}) - \mathbf{x}'_0 \boldsymbol{\beta} = 0 \text{ and} \\
V(\delta) &= V(\hat{y}_0 - E(y_0)) = V(\mathbf{x}'_0 \mathbf{b} - \mathbf{x}'_0 \boldsymbol{\beta}) = V(\mathbf{x}'_0 \mathbf{b}) \\
&= \mathbf{x}'_0 V(\mathbf{b}) \mathbf{x}_0 = \mathbf{x}'_0 (\sigma_\varepsilon^2 (\mathbf{X}'\mathbf{X})^{-1}) \mathbf{x}_0 = \sigma_\varepsilon^2 \mathbf{x}'_0 (\mathbf{X}'\mathbf{X})^{-1} \mathbf{x}_0.
\end{aligned}$$

However, if we are predicting an actual value \hat{y}_0 then we call an interval estimate a prediction interval, and we need to account for the variation of an observation about its mean. We can reflect this by writing the true value y_0 as $y_0 = \mathbf{x}'_0 \boldsymbol{\beta} + \varepsilon_0$, then we can define the error as $D \equiv \hat{y}_0 - y_0 = \mathbf{x}'_0 \mathbf{b} - (\mathbf{x}'_0 \boldsymbol{\beta} + \varepsilon_0) = \mathbf{x}'_0 (\mathbf{b} - \boldsymbol{\beta}) - \varepsilon_0$. Then we see that:

$$\begin{aligned}
E(D) &= E(\mathbf{x}'_0 (\mathbf{b} - \boldsymbol{\beta}) - \varepsilon_0) = \mathbf{x}'_0 E(\mathbf{b} - \boldsymbol{\beta}) - E(\varepsilon_0) = 0 \text{ and} \\
V(D) &= V(\mathbf{x}'_0 (\mathbf{b} - \boldsymbol{\beta}) - \varepsilon_0) = \mathbf{x}'_0 V(\mathbf{b} - \boldsymbol{\beta}) \mathbf{x}_0 + V(\varepsilon_0) \\
&= \mathbf{x}'_0 V(\mathbf{b}) \mathbf{x}_0 + \sigma_\varepsilon^2 = \sigma_\varepsilon^2 \mathbf{x}'_0 (\mathbf{X}'\mathbf{X})^{-1} \mathbf{x}_0 + \sigma_\varepsilon^2 \\
&= \sigma_\varepsilon^2 (1 + \mathbf{x}'_0 (\mathbf{X}'\mathbf{X})^{-1} \mathbf{x}_0).
\end{aligned}$$

Clearly we are less certain in our forecast of a particular value than in our forecast of a mean value. Since we do not know the value of σ_ε^2 , we use S_E^2 as an estimate and use the t distribution for constructing confidence and prediction intervals.