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Lecture 2

Recall the problem

$$\frac{dp}{dt} = kp$$

with solution $p(t) = Ce^{kt}$, C is an arbitrary constant.

Condition $p(0) = 1000$ is called an initial condition (IC).

IC determines the unique solution out of infinitely many solutions defined by an arbitrary constant C .

IC specifies C

Def the order of a DE is the order of the highest derivative in DE.

Ex $y' = e^t$: 1st order DE
 $\frac{d^2x}{dt^2} + 9x = 0$: 2nd order DE

$$y'' + 3y^3 = 2x : \quad 2^{\text{nd}} \text{ order DE}$$

$$\frac{d^2y}{dx^2} - y \cdot y \cdot y$$

$$y^3 = y \cdot y \cdot y$$

$$y^{(4)} + y^2 x + y = dx : \quad 4^{\text{th}} \text{ order DE}$$

$$y'' = \frac{dy^4}{dx^4}$$

In general, n^{th} order DE for $y=y(x)$ can be written as

(1) $F(x, y, y', y'', \dots, y^{(n)}) = 0$

$F(x, y, y', y'', \dots, y^{(n)}) = 0$ is a solution of DE (1) on a continuous function $u=u(x)$ if some interval $x \in I$ if $F(x, u, u', \dots, u^{(n)}) \equiv 0$ for all $x \in I$

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If we have a DE for function $u(x)$ of one variable x ,
 then we have an ordinary differential equation (ODE)

Consider $u = u(t, x)$: temperature of a long thin rod uniform

then

$$(2) \quad \frac{\partial u}{\partial t} = k \frac{\partial^2 u}{\partial x^2}, \quad k > 0:$$

A side:

partial derivatives

Eg' (2) is a partial differential equation (PDE).

Math 480 - PDEs.

This is an ODE class.

$$z = x^2 \cdot \sin y$$

$$\frac{\partial z}{\partial x} = 2x \cdot \sin y$$

$$\frac{\partial z}{\partial y} = x^2 \cdot \cos y$$

$$z = \cos(x^2 y)$$

$$\frac{\partial z}{\partial x} = -\sin(x^2 y) \cdot 2xy$$

$$\frac{\partial z}{\partial y} = -\sin(x^2 y) \cdot x^2$$

$$\frac{\partial z}{\partial y} (x^2 y)$$

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We will start from 1st order DEs.

$$\int \frac{dy}{dx} = f(x, y)$$

$$\left\{ \begin{array}{l} y(x_0) = y_0 : \\ \text{DE + IC} \end{array} \right.$$

$$y = y(x)$$

IC

DE + IC form an initial value problem (IVP).

that

To solve IVP, we need to find a function $y = y(x)$ that satisfies both DE and IC.

1.2 Integrals as General and Particular Solutions

Consider

$$\frac{dy}{dx} = f(x)$$

no y

1st order DE

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We want to find solution $y(x)$.

$$y(x) = \int \frac{dy}{dx} dx = \int f(x) dx + C$$

arbitrary const

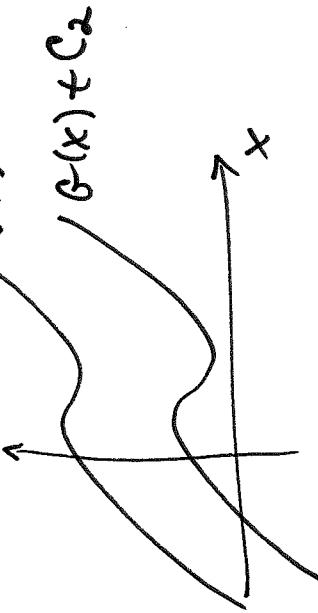
$y(x) = \int f(x) dx + C$

a general solution of DE

$\frac{dy}{dx} = f(x)$

A general solution of a 1st order DE involves an arbitrary constant. It defines a one-parameter family of solutions.

Let $G(x)$ be an antiderivative of $f(x)$, i.e. $G'(x) = f(x)$.



$y(x) = G(x) + C$

If we have IC $y(x_0) = y_0$.

\Rightarrow at $x=x_0$: $y(x_0) = \underbrace{G(x_0) + C}_{\text{"y}_0\text{"}}$ can evaluate

$C = y_0 - G(x_0)$

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$$\Rightarrow y(x) = G(x) + [y_0 - G(x_0)] \quad \text{the particular solution}$$

of DE $y' = f(x)$ subject to
IC $y(x_0) = y_0$.

Note The general solution
of a DE.

Ex Solve TVP

$$\frac{dy}{dx} = 4x - 5, \quad y(1) = 2$$

$$y(x) = \int (4x - 5) dx = 2x^2 - 5x + C : \quad \text{the general solution}$$

$$\text{At } x=1, \quad y(1) = 2$$

$$y(1) = 2 \cdot 1^2 - 5 \cdot 1 + C \Rightarrow 2 = 2 - 5 + C \Rightarrow C = 5$$

$$\therefore y(x) = 2x^2 - 5x + 5 : \quad \text{the particular solution}$$

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Consider

$$\frac{d^2y}{dx^2} = g(x) \quad : \quad \text{2nd order DE}$$

no of dependence

Integrate twice wrt x.

$$\begin{aligned}\frac{dy}{dx} &= \int \frac{d^2y}{dx^2} dx = \underbrace{\int g(x) dx}_{\text{"}''g(x)'} + C_1 = G(x) + C_1 \quad \xrightarrow{\text{arbitrary constants}} \\ y(x) &= \int \frac{dy}{dx} dx = \underbrace{\int [G(x) + C_1] dx}_{\text{"}''H(x)''} = \underbrace{\int G(x) dx}_{\text{"}''H(x)''} + C_1 x + C_2 = \\ &= H(x) + C_1 x + C_2\end{aligned}$$

a general solution of
2nd order DE $y'' = g(x)$

$$\boxed{y(x) = H(x) + C_1 x + C_2}$$

\therefore

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Velocity and Acceleration

$x(t)$: particle position

m : mass of particle

$F(t)$: force acting on the particle along its line of motion

$$\frac{dx}{dt} = v(t) : \text{velocity}$$

$$x(t) = \int v(t) dt$$

\Rightarrow

$$\frac{d^2x}{dt^2} = \frac{dv}{dt} = a(t) : \text{acceleration}$$

$$x(t) = \int_{t_0}^t v(\tau) d\tau + x(t_0)$$

' integral w/ upper
variable limit

$$\frac{d}{dt} x(t) = v(t) \Big|_{t=t} = v(t)$$

Newton's 2nd law of motion: $ma = F$

$$\Rightarrow m \frac{d^2x}{dt^2} = F : \quad \text{2nd order DE for } x(t)$$

$$x(0) = x_0 : \text{initial position}$$

$$\frac{dx}{dt}(0) = v_0 : \text{initial velocity}$$

Assume for simplicity that $F = \text{const} \Rightarrow a = \text{const}$

$$\frac{d^2x}{dt^2} = \frac{F}{m}$$

or

$$\frac{d^2x}{dt^2} = a$$

Integrate:

$$\frac{dx}{dt} = \int \frac{d^2x}{dt^2} dt = \int a dt = at + C_1$$

$$\boxed{C_1 = v_0}$$

$$\text{IC: } x(0) = x_0 \quad \Rightarrow \quad \text{at } t=0 :$$

$$\frac{dx}{dt}(0) = v_0$$

$$\boxed{\frac{dx}{dt} = at + v_0}$$

or

$$\boxed{v(t) = at + v_0}$$

$$\frac{dx}{dt} = a \underbrace{\cancel{t}}_{\parallel v_0} + C_1 \Rightarrow \boxed{C_1 = v_0}$$

Integrate again

$$x(t) = \int (at + v_0) dt = \frac{at^2}{2} + v_0 t + C_2$$

$$\text{IC: } x(0) = x_0 \Rightarrow x(0) = \frac{0^2}{2} + v_0 \cdot 0 + C_2 \Rightarrow C_2 = x_0$$

$$\therefore x(t) = \frac{a}{2} t^2 + v_0 t + x_0$$