## Lab 7 Report Topics and Questions

## ECE341, University of Idaho

## Demonstration

In addition to the specifications in the lab handout:

- Your design must be modular. This means that you must have a source file and header for each subsystem. The four primary subsystems are listed below:
  - LCD
    - \* Copy LCDLib.c and LCDLib.h
  - UART
    - \* Copy the supplied code from comm.c and comm.h
  - Buttons:
    - \* Change Notice ISR
    - \* Decode buttons
  - Stepper Motor:
    - $\ast~{\rm Timer1~ISR}$
    - \* Stepper state machine
    - \* Stepper code output
- Each subsystem must have its own initialization function, and a header that prototypes the functions in its respective source file. Note: you can use **extern** to access global variables that are declared in a different C file.
- The source file that contains main should include the header files for each peripheral, call the subsystem initialization functions, and facilitate the data transfer between subsystems.
- Each subsystem must be individually testable, meaning that each subsystem could be instantiated into a new project and tested without the other subsystems.

## Report

- In the implementation section:
  - Why are the UART receive functions (getstrU1, getcU1) in the background? What would happen if they were in the foreground?
  - What is the purpose of the \_mon\_putc function?
  - The CFD for the project must include the CFD sub-diagram for the function getstrU1. Essentially, read and understand the code that was supplied to you and use it to derive a CFD.
- In the testing and verification section:
  - Describe how each subsystem was incorporated into the project.
  - When a subsystem was added, how did you test it? Describe the testing process for each subsystem.
- In the conclusion:
  - Address the advantages and disadvantages of serial and parallel communications. When might it be better to use one over the other? Support your answer with examples.
  - Why is it important for a design to be modular?